A Forecasting Analysis of Risk-Neutral Equity and

Treasury Volatilities

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Abstract

This paper employs the equity (VIX) and Treasury (MOVE) risk-neutral volatilities to assess their relative forecasting performance with respect to future real activity, stock and Treasury excess returns, and aggregate risk factors. The in-sample evidence suggests that the square of VIX tends to dominate the square of MOVE. The out-of-sample predicting analysis, which is performed as a horse race between equity and Treasury risk-neutral volatilities shows that, contrary to the previous results, both the square of VIX and MOVE tend to complement each other.

Keywords: risk-neutral equity volatility, risk-neutral treasury volatility, predictability of real activity and asset returns

JEL classification: C53, G12, G13

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1. Introduction

The VIX index is the risk-neutral one-month expected stock market volatility for the U.S. S&P500 index. It is computed by averaging the weighted prices of puts and calls on the S&P500 index over a wide range of strike prices. It has become an extremely popular and useful measure of near-term market volatility. It is surprising that the extant and large literature on implied volatility has almost exclusively engaged on equity markets.¹

Indeed, by noting the lack of evidence about the relative importance between risk-neutral equity and Treasury volatilities, the main contribution of this paper is to fill partially this gap by analyzing the forecasting performance of both types of risk-neutral volatilities. Specifically, we perform an in-sample, and a competing out-of-sample forecasting analysis between VIX and the Treasury risk-neutral volatility regarding future real activity, as well as future financial returns. This may be especially informative given the recent findings of Gonzalez-Urteaga, Nieto and Rubio (2018). They study the connectedness dynamics between both types of risk-neutral volatilities, and show that most of the time, but especially during bad economic times, the Treasury risk-neutral volatility is a net sender of volatility to VIX. They also detect that both monetary policy and economic drivers explain the spillover dynamics between both risk-neutral volatilities.

We employ the MOVE index, which is the Merrill Lynch Option Volatility Estimate Index, as the Treasuries implied volatility. It is a term structure index of the normalized implied volatility on one-month Treasury options which are weighted on the

¹ Notable exceptions are Choi, Mueller, and Vedolin (2017) and Mueller, Sabtchevsky, Vedolin, and Whelan (2016), who analyze the market variance risk premium in both equity and Treasury markets, and Mele, Obauashi, and Shalen (2015), who study the information contained in VIX and the interest rate swap rate volatility index known as SRVX.

2, 5, 10, and 30-year contracts. It is therefore the equivalent of VIX for Treasury bond returns and reflects the market-based measure of uncertainty about the composite future behavior of interest rates across different maturities of the yield curve. Current increases in MOVE suggests that the market is willing to pay more for hedging against unexpected movement in interest rates.

Given the evidence reported by Adrian, Crump, and Vogt (2018) pointing out the importance of nonlinearities, our analysis of forecasting employs the square of VIX and MOVE rather than the volatilities themselves. The in-sample relative forecasting ability of VIX² and MOVE² suggests that VIX² tends to dominate MOVE² in both real activity and financial returns. Although, it is important to recall that González-Urteaga et al. (2018) show that MOVE is a net contributor of volatility to VIX. This transmitted information may be helping VIX in improving its forecasting capacity of future output and financial returns.

On the other hand, the out-of-sample forecasting improvement of VIX² over $MOVE^2$ and vice versa is mixed when predicting either real activity, the stock market, or Treasury bond returns. Both VIX² and $MOVE^2$ complement each other in these forecasting exercises. However, VIX² tends to outperform $MOVE^2$ when forecasting aggregate risk factors on out-of-sample basis.

This paper proceeds as follows. Section 2 presents a brief discussion of the behavior of VIX and MOVE and describes the data employed in the analysis. Section 3 describes the decomposition of VIX and MOVE into their uncertainty and risk aversion components. Section 4 presents the in-sample predicting ability of equity and Treasury risk-neutral volatilities, while Section 5 contains the out-of-sample forecasting analysis.

Finally, Section 6 presents our conclusions. The Appendix shows the detailed out-of-sample forecasting results.

2. Data and a Preliminary Analysis of VIX and MOVE

We collected daily and monthly data for VIX and MOVE from April 4, 1988 to October 5, 2017, where the monthly data refers to the last observation in each month throughout the sample period.²

Figure 1 shows the annualized daily behavior of VIX and MOVE. As expected, risk-neutral volatilities are countercyclical, and the spikes during economic crisis are much larger in equity than in Treasury volatilities. On daily basis, the minimum (9.2%) and maximum (80.9%) levels for VIX were reached on October 5, 2017 and November 20, 2008, respectively, whereas for MOVE the minimum (4.7%) and maximum (26.5%) were observed in August 7, 2017 and October 10, 2008, respectively. In Figure 2, we show how volatile VIX and MOVE are. It displays the monthly volatility of both risk-neutral volatilities estimated with daily data within each month in our sample. It is a measure of financial uncertainty in the equity and Treasury bond markets, respectively. As expected, VIX seems to be much more volatile than MOVE with much larger spikes during bad news economic times.

Table 1 contains summary statistics for VIX and MOVE obtained from monthly data from April 1988 to September 2017 using observations on the last day of the month. During the full sample period, the average risk-neutral volatility for the stock

² VIX was downloaded from <u>www.cboe.com</u> and MOVE from Bloomberg. Since MOVE is available from April 1988, we employ VXO (the risk-neutral market volatility for the U.S. S&P100 index) from April 1988 to December 1989. Starting in January 2003, the CBOE launched the 10-year Treasury Note Volatility Index (TYVIX), which measures a constant 30-day risk-neutral expected volatility on 10-year Treasury Note futures prices. Given that MOVE is available for a much longer sample period, this research employs MOVE rather than TYVIX. The correlation between both series using monthly data (the quote in the last day of each month) from January 2003 to September 2017 is 0.953.

market is 19.5%, whereas the risk-neutral volatility for Treasuries is much lower and equal to 9.7% approximately. VIX is also much more volatile than MOVE, and similarly, the range between the minimum and maximum values moves from 9.5% to 59.9% for VIX whereas it goes from 4.8% to 21.4% for MOVE.³ VIX presents much higher positive skewness and kurtosis than MOVE. Finally, both implies volatilities are highly persistent with autocorrelation coefficients of 0.84 and 0.85 for VIX and MOVE, respectively.

We next describe the data used in the forecasting analysis. All the competing or control variables that we employ together with VIX and MOVE have been shown to be strong predictors in previous literature. We employ two variables regarding the behavior of interest rates. First, the slope of the term structure denoted as TERM, which is the difference between the yield of the 10-year government bond and the 3-month Treasury bill rate. TERM is one of the most popular forecasting instruments of real activity. Increases in the slope of the term structure have been shown to predict higher future growth rates of economic activity, whereas decreases in the slope tend to predict bad economic times.⁴ Moreover, Choi et al. (2017) employ an options panel data set on Treasury futures to show that the term structure of risk-neutral variances is downward sloping and significantly related to economic conditions. Given that MOVE includes data on 2, 5, 10, and 30-year contracts, it seems reasonable to include TERM in the regression model. Second, to consider inflation risk, we employ the expected inflation for a one-year horizon denoted as EINF. It is downloaded from the Federal Reserve Bank of Cleveland. Their model employs Treasury yields, inflation rate data, inflation swaps, and survey-based measures of future inflation to estimate expected inflation to

³ To be precise, the coefficients of variation are 0.38 and 0.27 for VIX and MOVE, respectively.

⁴ Among many others, see Stock and Watson (2003).

alternative horizons. In this research, *EINF* is employed as one the key variables to obtain the expected (physical) future variance of Treasury bond returns. In other words, it is a variable used to estimate the uncertainty component of MOVE rather than a direct predictor of future real activity or financial returns.

Regarding credit risk, Gilchrist and Zakrajsek (2012) show the forecasting power of the term structure of credit spreads for future output growth. These authors argue that there is a pure credit component orthogonal to macroeconomic conditions that accounts for a large part of the predicting capacity of credit spreads. Given that we work with risk-neutral volatilities, it is also important to note that González-Urteaga and Rubio (2016) show that the default premium, denoted as *DEF*, is a key factor explaining the cross-sectional variation of equity volatility risk premia. It seems therefore natural to employ the default spread, calculated as the difference between Moody's yield on Baa corporate bonds and the 10-year government bond yield, as a potentially relevant control variable. Both yields are obtained from the Federal Reserve Statistical Release.

The most popular predictor, at least of future equity returns, is the aggregate dividend yield, which we denote as DY. As discussed by Cochrane (2011), the time-varying behavior of the expected market risk premium has a clear correlation with the business cycle. He shows that, indeed, the DY is a strong forecaster of the future market risk premium and, therefore, it becomes a potential state variable for forecasting real activity.⁵ We also employ the Hansen–Jagannathan (1991) volatility bound, denoted as *HJ VOL*, as an additional predictor. Nieto and Rubio (2014) propose how to extract future real activity information from optimally combined size-sorted portfolios. Specifically, they show that a size-based volatility bound of the stochastic discount

⁵ The dividend yield in logs is computed from the original series on Robert Shiller's website (<u>http://www.econ.yale.edu/~shiller/</u>).

factor is a powerful in-sample and out-of-sample predictor of future industrial production growth. Finally, given the discussion of Brunnermeier and Pedersen (2009), we propose *TED* as a proxy for funding liquidity, and as an additional predictor variable. *TED* is the spread between the 3-month LIBOR based on U.S. dollars and 3-month Treasury Bill.

We also collect data on the variables to be predicted. As a measure of real economic activity, we employ monthly data of the Industrial Production Index (*IPI*). These data are downloaded from the Federal Reserve, with series identifier G17/IP Major Industry Groups. We obtain data on the excess return of the composite index of 5-, 10-, and 30-year horizons of Treasury bonds, denoted as *TRYRET*, which is downloaded from https://fred.stlouisfed.org/.

In addition, we study the forecasting ability of VIX and MOVE with respect to the aggregate risk factors from the Fama and French (2015) five-factor model, which expands their popular three-factor model with profitability (robust minus weak, *RMW*) and investment (aggressive minus conservative, *CMA*) factors. We denote the excess market portfolio return as *EXCMKET*, and the size and value factors as *SMB* and *HML*, respectively. Moreover, given that they are not able to explain the cross-sectional variability of momentum portfolios unless Carhart's (1997) momentum factor (*MOM*) is included in the cross section, we consider this factor in our analysis. We collect these monthly data from Kenneth French's website (<u>http://mba.tuck.darmouth.edu</u>).

We also use the Quality minus Junk (*QMJ*) factor of Asness, Frazzini, and Pedersen (2014), further explored by Asness, Frazzini, Israel, Moskowitz, and Pedersen (2018). These authors define a quality stock as an asset for which an investor would be willing to pay a higher price. These are stocks that are safe (low required rate of return),

profitable (high return on equity), growing (high cash flow growth), and well managed (high dividend payout ratio). Asness et al. (2014) show that the *QMJ* factor, which buys high-quality stocks and shorts low-quality (junk) stocks, earns significant risk-adjusted returns not only in the U.S. market but also in 24 other countries. The *QMJ* factor is downloaded from the AQR Capital Management Database (<u>www.aqr.com</u>).

Finally, recent empirical evidence supports the presence of funding liquidity across a wide range of securities. Frazzini and Pedersen (2014) show that leverage constraints are strong and significantly reflected in the return differential between leveraged low-beta stocks and de-leveraged high-beta stocks. The authors argue that the positive and highly significant risk-adjusted returns relative to traditional asset pricing models shown by portfolios sorted by the level of market beta are explained by shadow cost-of-borrowing constraints.⁶ The authors illustrate their argument by proposing a market neutral *BAB* factor consisting of the difference between long-leveraged low-beta stocks and short de-leveraged high-beta securities. This factor is downloaded from the AQR Capital Management Database.

3. A Simple Decomposition of Risk-Neutral Equity and Treasury Variances

As discussed by Bekaert and Hoerova (2014), the squared VIX reflects both stock market uncertainty and risk aversion. Uncertainty is captured by the physical expected variance, while risk aversion is proxied by the variance risk premium (*VRP*), which is the expected risk premium from selling equity variance in swap contracts. The equity variance risk premium is defined as

$$VRP_t^E = E_t^P \left(RVAR_{t+1}^E \right) - VIX_t^2, \tag{1}$$

⁶ See also Asness, Frazzini, Gormsen, and Pedersen (2018) for additional evidence supporting this argument.

where VRP_t^E is the equity variance risk premium, and $E_t^P(RVAR_{t+1}^E)$ is the expected conditional value of the future realized variance of equity returns under the physical probability *P*.

There is an extensive literature using these components as potential predictors of stock markets returns and industrial production growth. Bollerslev, Tauchen and Zhou (2009) show that the variance risk premium predicts future stock returns, and Bekaert and Hoerova (2014), using an improved model specification of volatility, show that the variance risk premium (risk aversion) has predictive power of future equity returns, but real activity is significantly predicted by the conditional stock market variance (uncertainty). Indeed, in bivariate regressions using both the VRP and the conditional variance, they show that the VRP is an overall better predictor of future stock returns than the conditional variance, and that the squared of VIX fails to forecast future returns. On the other hand, opposite results are reported when predicting future real activity. The expected conditional variance is a stronger predictor of future production growth. More recently, Fan, Xiao, and Zhou (2018) propose a decomposition of the equity VRP into a pure second order VRP and a higher order risk premium. It turns out that the VRP displays short-term predictive power for future returns, but the higher order risk premium contains a medium-term forecasting ability. More importantly, this decomposition improves the market return forecasting both in-sample and out-ofsample. Finally, when predicting either real activity or financial returns, it is important to employ the risk-neutral variance of market equity as predictor rather than volatility itself. Adrian, Crump, and Vogt (2017) argue that VIX strongly forecasts stock and bond returns up to 24 month-horizon when the nonlinearity is accounted for. This result may be associated with the recent findings of Danielsson, Valenzuela, and Zer (2018),

who argue that volatility itself is not a significant predictor of financial crises, but unusually high and low volatilities are.

Under the same arguments, the Treasury VRP is defined as

$$VRP_t^T = E_t^P \left(RVAR_{t+1}^T \right) - MOVE_t^2,$$
⁽²⁾

where VRP_t^T is the Treasury variance risk premium, and $E_t^P(RVAR_{t+1}^T)$ is the expected conditional value of the future realized variance of (composite) Treasury returns under the physical probability *P*.

In a parallel research to the literature of the equity variance risk premium and using their own data on risk-neutral variance of Treasury returns, Choi et al. (2017) show that the term structure of implied Treasury variances is downward sloping, and that the slope has predictive power for future real activity at short horizons. Moreover, Mueller et al. (2016) report that short-term VRP_t^T predicts future bond returns at short-term horizons, and long-term VRP_t^T forecasts bond returns at longer horizons.

We next decompose risk-neutral variances into expected physical variances and the variance risk premium. There is a huge literature on the econometrics of volatility forecasting. Rather than using high-frequency data and jumps in the spirit of Andersen, Bollerslev, and Diebold (2007), and the threshold bipower variation proposed by Corsi, Pirino, and Renò (2010), we follow a simple but powerful approach suggested by Zhou (2018) in which the square of VIX and the past realized variances are employed as independent variables. Therefore, for the case of the expected realized variance of equity returns we forecast future realized variance as:

$$\hat{E}_t \left(RVAR_{t+1}^E \right) = \hat{\beta}_0 + \hat{\beta}_1 VIX_t^2 + \hat{\beta}_2 RVAR_t^E .$$
(3)

In our sample period, simple regressions show that these two predictors explain approximately 85% of the variability of future realized equity variance.

We follow a similar approach for the expected realized variance of Treasury returns. In this case, however, we also add the expected (one year-horizon) inflation, which we find to be a powerful predictor of future realized variance of Treasuries. The following model gives the expected (physical) future variance of Treasury bond returns:

$$\hat{E}_t \left(RVAR_{t+1}^T \right) = \hat{\beta}_0 + \hat{\beta}_1 MOVE_t^2 + \hat{\beta}_2 RVAR_t^T + \hat{\beta}_3 EINF_t.$$
(4)

In this case, OLS regressions show that the dependent variables explain around 66% of the variability of future realized variance of Treasury returns.

Figures 3 displays the conditional variances of equities and Treasury bonds using expressions (3) and (4), and Figure 4 the corresponding variance risk premia. Although, the recession-associated peaks are clear in both figures, we also observe relevant differences among them, which motivates the competing analysis of both types of risk-neutral volatilities for forecasting returns and real activity.

4. The In-Sample Predictability of Real Economic Activity and Financial Returns with VIX² and MOVE²

Tables 2 to 6 contain the results of forecasting industrial production and several types of financial asset returns with one-, 3-, 6-, and 12-month horizons. In all cases we run a similar in-sample predicting regression,

$$Y_{t,t+\tau} = \alpha + \beta_l X_t + \beta' Controls_t + \varepsilon_{t,t+\tau}, \ \tau = 1,3,6,12,$$
(5)

where $Y_{t,t+\tau}$ is either future real activity growth, $\Delta IPI_{t,t+\tau}$, future excess market return, $EXCMKET_{t,t+\tau}$, future excess Treasury bond return, $TRYRET_{t,t+\tau}$, future $HML_{t,t+\tau}$, or future $BAB_{t,t+\tau}$.⁷ The predictor X_t is either VIX² or MOVE² or the variance risk premia and the expected realized variances given by equations (1), (2), (3), and (4). All regressions control for the usual predictors employed in literature. We include the lagged value of the dependent variable, the TERM and default (DEF) spreads, the logarithm of the dividend yield (DY), the TED spread, and the size-based model-free Hansen and Jagannathan (1991) volatility bound (HJ VOL). In each panel and for each horizon, we employ the set of controls that maximize the R-squared statistic. For saving space, we only report the intercept, and the slope estimated coefficient, β_l . It is well known that the overlap in the monthly data generates serial correlation in the disturbance term that must be corrected when calculating standard error. Following Bekaert and Hoerova (2014), we use the Newey-West (1987) HAC standard errors that may improve power over the Hodrick (1992) errors as long as we select a large number of lags.

Table 2 shows the forecasting results for the industrial production growth for the four alternative horizons. In Panel A of Table 2, we report that the squared of VIX fails to predict real activity. However, as in Bekaert and Hoerova (2014), the conditional expected realized variance is a significant predictor of production growth with the expected negative sign at the shortest horizon, and at the 3-month horizon with an adjusted *t*-statistic of 1.67. Therefore, increases of the conditional equity variance tend to decrease real activity at relatively short horizons. On top of that, the equity *VRP* is

⁷As discussed later, *HML* and *BAB* are the only two risk factors for which VIX and/or MOVE show a significant forecasting capacity. To save space, we have decided not to report these results because they do not add any relevant information. In any case, all results are available from the authors upon request.

also a significant predictor of real activity with the same negative sign at the shortest horizon. Indeed, for the one-month horizon, the slope coefficient is estimated with relatively more precision than the coefficient for the expected conditional variance. Higher equity-related uncertainty and/or risk aversion seem to be associated with a decrease in real activity in the short-run. Note that at longer horizons nor VIX² neither its components forecast significantly real activity. However, the *R*-squared statistic increases from 0.20 approximately at the shortest horizon to 0.40 and 0.32 at the 3- and 6-month horizons, respectively indicating that other instruments contain relevant information about future real activity.

Panel B of Table 2 clearly shows that either $MOVE^2$ or its components fail to predict future real activity. At the shortest horizon, the expected variance and the *VRP* have the same signs as in the case of equity variance. However, none of them are statistically different from zero. Note that the *R*-squared value reflects the relative importance of the controls employed in each of the regressions. It does not reflect the relative predicting ability of VIX² or MOVE². It is also important to recall the evidence reported by González-Urteaga et al. (2018), who show that the volatility spillovers from MOVE to VIX are strong and statistically significant especially during bad economic times. Hence, our new evidence suggests that the information content captured from MOVE by VIX may be a key source of the embedded signal explaining the forecasting ability of the uncertainty and risk aversion components of VIX². It seems that the combined information contained in VIX through its idiosyncratic information and the information sent by MOVE to VIX makes the components of VIX to be strong forecasters of real activity at relatively short horizons.

Panels A and B of Table 3 shows the results regarding the future excess market return. The risk-neutral variance shows a significant and positive predictive power of future returns at the 6- and 12-month horizon. Therefore, the two components of VIX² predict real activity at short horizons with a negative sign, while the expected variance component predicts stock returns at medium-long horizons with a positive sign, which suggests a positive relation between the conditional variance and expected excess returns. This reflects the (theoretically expected) positive sign of the relation between risk and return for equity aggregate returns. As for real activity, $MOVE^2$ does not seem to be able to predict future equity returns, although the *VRP* associated with Treasuries presents a positive coefficient with a *t*-statistic of 1.57 at the shortest horizon. Again, given the connectedness dynamics evidence reported by González-Urteaga et al. (2018), this does not necessarily mean that MOVE does not have relevant information with respect to future market returns.

Panels A and B of Table 4 show the forecasting results of the (composite) Treasury excess returns. Neither VIX² nor MOVE² are significant predictors of Treasury excess returns. However, the equity VRP is a powerful predictor of future Treasury returns with negative and statistically significant coefficients at the 3-, 6-, and 12-month horizons. As before, it seems very plausible that this result may be partially due to the spillover information from MOVE to VIX already discussed above. Overall, at medium and long horizons, the in-sample results suggest that the expected variance of equity forecasts future equity returns, but the equity *VRP* forecasts Treasury bond returns.

Along this research, we check for the forecasting ability of risk-neutral variances regarding well-known aggregate risk factors. We analyze the five Fama-French (2015) factors, the momentum (*MOM*) factor of Carhart (1997), the Quality minus Junk (*QMJ*) factor of Asness et al. (2014), and Asness et al. (2018), and the Betting against Beta Factor (*BAB*) of Frazzini and Pedersen (2014). Overall, risk-neutral variances of either

equity or Treasury bonds fail to predict risk factors. However, we find that risk-neutral variances do predict both *HML* and *BAB* at short horizons. To the best of our knowledge, this is the first time that this evidence has been reported. Recall that the differences between dynamic market betas of value and growth companies tend to be very large during bad economic times, and the *BAB* factor reflects funding liquidity and tends to have highly negative returns in bad times. It is interesting that precisely the *HML* and the *BAB* factors are the ones for which risk-neutral variances have predictive power.

The results for the *HML* and *BAB* factors are shown in Panels A and B of Tables 5 and 6, respectively. The VIX² significantly predicts both the *HML* and *BAB* factors with a negative sign at short horizons. Both results are estimated with high statistical precision. Increases in the square of VIX strongly signals future bad times as proxied by negative realized returns (or high expected returns) in the *HML* and *BAB* factors. Interestingly, this holds even though the uncertainty and risk aversion components of VIX² affect very differently *HML* and *BAB*. In the case of the *HML* factor, it is the expected variance component (and not the *VRP* component) that shows forecasting ability. However, in the case of the *BAB* factor, it is the expected variance) that has predictive ability. The future behavior of the *HML* factor seems to be related more with uncertainty, while the *BAB* factor responds more to risk aversion.

On the other hand, $MOVE^2$ fails to predict either *HML* or *BAB*. But, the Treasury *VRP* component significantly predicts *HML* at the shortest and medium horizons, and *BAB* at the 3-month horizon, both with positive signs.

5. The Out-of-Sample Predictability of Real Economic Activity and Financial Returns with VIX² and MOVE²: A Comparison Analysis

In this Section, we describe the tests and discuss the results of the out-of-sample forecasts of future real economic activity, and future financial returns for stocks, Treasury bonds and the *HML* and *BAB* factors using either VIX² or MOVE². Which of the two risk-neutral volatilities are stronger predictors of future activity and asset returns? We employ two alternative statistics to test the out-of-sample accuracy of two (VIX² versus MOVE²) competing models: the *t*-test proposed by Diebold and Mariano (1995) and the *F*-statistic of McCracken (2007). In our case, the two compared models are always nested. The restricted model contains only one predicting variable: either VIX² or MOVE², or the lagged dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound, and *TED*. Given the in-sample forecasting evidence, the predictor is selected among the best predictors in that context across all dependent variables and horizons. The unrestricted model contains that individual predictor in the restricted model and either MOVE² or VIX².

We now briefly describe this methodology. The total sample period contains T + P observations, where the initial in-sample estimation period employs information from one to T and the out-of-sample forecasting period is from $T + \tau$ to T + P, τ being the forecasting horizon. At each forecasting period $t = T + \tau$, ..., T + P, we estimate the two competing nested models using information up to the previous τ periods, generate the prediction, and compute the forecasting error. More formally, the restricted model is

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$$Y_{s} = \alpha^{R} + \beta_{l}^{R} X_{s-\tau} + u_{Rs} , s = \tau + 1..., t - \tau,$$
(6)

where Y_s is one of the followings: industrial production growth, excess market returns, excess Treasury bond returns, *HML* or *BAB*, and X_s is one of the competing predictors including VIX² or MOVE².

The prediction under the restricted model is

$$\hat{Y}_{Rs} = \hat{\alpha}^R + \hat{\beta}_I^R X_{s-\tau}.$$
(7)

and the prediction error is

$$\hat{u}_{Rt} = Y_t - \hat{Y}_{Rt} \,. \tag{8}$$

Similarly, the unrestricted model includes the forecasting individual variable in the restricted model and either $MOVE^2$ or VIX^2 , denoted as Z_s in the following equation:

$$Y_{s} = \alpha^{U} + \beta_{1}^{U} X_{s-\tau} + \beta_{2}^{U} Z_{s-\tau} + u_{Us} , s = \tau + 1..., t - \tau.$$
(9)

The unrestricted prediction and forecasting error are

$$\hat{Y}_{Us} = \hat{\alpha}^U + \hat{\beta}_I^U X_{s-\tau} + \hat{\beta}_2^U Z_{s-\tau},$$
(10)

$$\hat{u}_{Ut} = Y_t - \hat{Y}_{Ut},\tag{11}$$

where Z_s is any of the competing predictors including VIX² and MOVE². We next compute the vector of loss differentials, denoted *d*, which compares the two square errors at each month *t* and the mean-squared forecasting error (*MSE*) for each model:

$$d_t = \hat{u}_{Rt}^2 - \hat{u}_{Ut}^2 , \ t = T + \tau \dots T + P , \qquad (12)$$

$$MSE_{R} = (P - \tau + I)^{-1} \sum_{t=T+\tau}^{T+P} \hat{u}_{Rt}^{2} , \qquad (13)$$

$$MSE_{U} = (P - \tau + I)^{-1} \sum_{t=T+\tau}^{T+P} \hat{u}_{Ut}^{2} .$$
 (14)

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The two statistics for testing equal forecasting accuracy have the null that the loss differentials are zero, on average. The Diebold–Mariano (1995) statistic is a *t*-test expressed as

$$MSE(t) = \left(P - \tau + I\right)^{-1/2} \frac{\overline{d}}{\sqrt{\hat{S}_d}},\tag{15}$$

where $\overline{d} = (P - \tau + I)^{-1} \sum_{t=T+\tau}^{T+P} d_t$ and \hat{S}_d is a consistent estimator of the variance of the

loss differential that admits heteroskedasticity and autocorrelation. We employ the Newey–West (1987) specification and, following Clark and McCracken (2012), a lag length $k = 1.5 \tau$. Hence

$$\hat{S}_{d} = \sum_{j=-k}^{k} \left(\frac{k - |j|}{k} \right) \left(P - \tau - j + l \right)^{-l} \sum_{t=T+\tau}^{T+P} \left(d_{t} - \overline{d} \right) \left(d_{t-j} - \overline{d} \right).$$
(16)

The McCracken (2007) statistic is an F-test given by

$$MSE(F) = \left(P - \tau + I\right) \frac{MSE_R - MSE_U}{MSE_U}.$$
(17)

It must be noted that the loss differentials are measured with an error since the beta coefficients are unknown. This implies that the exact distribution of both statistics is also unknown and that the asymptotic distribution can only be obtained under restrictive assumptions that include non-nested models.⁸ For the case of nested models, Clark and McCracken (2012) suggest deriving the asymptotic distribution by a fixed regressor bootstrap and show that the test statistics based on the proposed bootstrap have good size properties and better finite-sample power than alternative bootstraps. This method is based on the wild fixed regressor bootstrap developed by Gonçalves and

⁸ See West (1996) and Clark and McCracken (2001) for a discussion.

Killian (2004) but adapted to the multi-step framework of out-of-sample forecasts. To implement this method, we use the followings steps:

1. We estimate both the restricted and unrestricted models using the full sample period. We save the coefficients of the restricted model and compute the residuals from the unrestricted model:

$$\hat{u}_{Ut} = Y_t - \hat{\alpha}^U - \hat{\beta}_1^U X_{s-\tau} - \hat{\beta}_2^U Z_{s-\tau} , \ t = l + \tau \dots T + P.$$

2. We assume and estimate an MA $(\tau - 1)$ process to capture the implicit serial correlation in the residuals from a τ -step-ahead forecast,

$$\hat{u}_{Ut} = \varepsilon_t + \theta_I \varepsilon_{t-1} + \ldots + \theta_{\tau-1} \varepsilon_{t-(\tau-1)}, \ t = l + \tau \ldots T + P$$

3. We simulate a sequence of independent and identically distributed N(0,1) random variables denoted by η_t and generate artificial residuals by using the estimates of the MA process:

$$\hat{u}_{Ut}^* = \eta_t \hat{\varepsilon}_t + \hat{\theta}_l \eta_{t-l} \hat{\varepsilon}_{t-l} + \ldots + \hat{\theta}_{\tau-l} \eta_{t-(\tau-l)} \hat{\varepsilon}_{t-(\tau-l)}, \ t = l + \tau \ldots T + P.$$

4. We simulate an artificial series of the dependent variable using the artificial residual and imposing the null hypothesis that the additional variable, Z_s , does not predict:

$$\hat{Y_t^*} = \hat{\alpha}^R + \hat{\beta}_l^R X_{s-\tau} + u_{Ut}^* , \ t = 2\tau + 1 \dots T + P .$$

5. We compute both the MSE(t)-statistics and MSE(F)-statistics using these artificial data as if they were the original data.

6. We repeat steps 3 to 5 5,000 times and the p-value is the percentage of times the simulated statistic is greater than the real statistic.

Our purpose is not to do a general horse race to decide which is the best predicting model, but we are interested in the forecasting performance of VIX^2 versus

MOVE². Our purpose is not to do a general horse race to decide which is the best predicting model. Therefore, we concentrate on the predicting competency of the equity and Treasury risk-neutral variances. Table 7 contains a summary of the out-of-sample comparative results between VIX² and MOVE². We employ the relative mean squared error suggested by Clark and McCracken (2012), which is given by $RMSE = \sqrt{MSE^U} / \sqrt{MSE^R}$, where the restricted and unrestricted *MSE* are given by equations (13) and (14), respectively. We also report the *p*-values associated with the null that the *t*-based *MSE* or the *F*-based *MSE* of expressions (15) and (17) are equal to zero, respectively. When the *RMSE* statistic is significantly less than one implies that the inclusion of either VIX² or MOVE² improves the out-of-sample forecasting capacity of the competing predictor.

Panel A of Table 7 shows the out-of-sample forecasting exercise of future real activity. At the shortest horizon, neither VIX² nor MOVE² significantly outperforms the other. However, both volatilities are equally necessary to forecast at the 3- and 6-month horizons, and both fail to improve prediction of industrial production growth over each other at the longest horizon. Note that at the 12-month horizon, the *p*-value of the *t*-statistic indicates that we can reject that both forecasting errors are equal, but the inclusion of MOVE² in addition to VIX² make the forecasting errors to be higher since *RMSE* is larger than one. Panel B of Table 7 shows that at the shortest horizon and at the 10% level, MOVE² better predicts future stock market excess returns than VIX². This is an important result. Recall that in bad economic times, the directional connectedness from MOVE to VIX dominates the effects of VIX over MOVE. However, for the rest of the horizons, both risk-neutral volatilities are equally relevant. On the contrary, in Panel C of Table 7 and regarding Treasury excess returns but, at the

longest horizon, the opposite results is obtained. $MOVE^2$ is a superior predictor of Treasury returns at the 12-month horizon. In Panel D, we show that VIX² significantly outperforms $MOVE^2$ when predicting *HML* at the 3-month horizon, but there is nothing statistically significant over and above this result. Finally, in Panel D of Table 7, we show that VIX² significantly improves the forecasting of the *BAB* over $MOVE^2$ for both, the shortest and longest horizons. This result suggests that funding liquidity, as proxied by *BAB*, is closely related to the previous behavior of the stock market risk-neutral volatility, at least for extreme horizons. Overall, VIX² significantly outperforms $MOVE^2$ in 4 out of 20 cases, while $MOVE^2$ improves VIX^2 only in 2 cases. VIX^2 (relative to $MOVE^2$) is a necessary predictor in 45% of the cases, and $MOVE^2$ (relative to VIX^2) in 25% of all possibilities. The only obvious advantage of VIX^2 over $MOVE^2$ seems to be concentrated on forecasting the *HML* and *BAB* risk factors.⁹

6. Conclusions

The empirical evidence regarding the relative forecasting ability between the equity risk-neutral variance and the Treasury risk-neutral variances is surprisingly scarce. This paper contributes to literature by performing a competing forecasting analysis between both implied variances. The in-sample analysis shows that VIX² dominates MOVE² either directly or indirectly through its uncertainty and risk aversion components. At the shortest horizon, increases in the expected conditional variance of equity returns and/or its variance risk premium are associated with a future decrease in real activity, while we find a significant opposite sign with respect to future market returns at long horizons. Similar to real activity, increases in the variance risk premium of equity returns decreases Treasury returns at the three longest horizons. Interestingly, given the

⁹ The detailed out-of-sample forecasting results using the procedure described above are reported in Tables A.1 through A.5 in Appendix.

counter-cyclical variation of the *HML* and *BAB* factors, we find that VIX^2 and its uncertainty component are significant forecasters of both factors but with the opposite sign to the one reported for the market excess returns, and at short rather than at long horizons. Both VIX^2 and its expected conditional variance component have a negative relation with the future behavior of *HML*, and VIX^2 also has a significant and negative relation with future returns of the *BAB* portfolio. Once again, this is the case at the shortest horizons. Moreover, the equity variance risk premium has a positive correlation with the future behavior of the *BAB* factor, while the Treasury variance risk premium has a positive relation with the future behavior of both the *HML* and *BAB* factors.

On the other hand, our out-of-sample predicting exercise shows that, overall, for future real activity and future excess market returns, and for most of the horizons, both VIX² and MOVE² complement each other. Both risk-neutral volatilities seem to be important when using an out-of-sample framework, at least regarding real activity and market returns. Neither one seems to dominate the other in terms of the out-of-sample predictability of future real activity. VIX² improves the forecasting of Treasury bond returns at the shortest horizon, while MOVE² improves the forecasting capacity of the stock market and Treasury bond returns at the shortest and longest horizons, respectively. Note that González-Urteaga et al. (2018) report that the total unconditional connectedness from 1988 to 2017 between VIX and MOVE is 28%, which suggests that, on average, there are idiosyncratic components that may explain our out-of-sample forecasting results in terms of the complementary results between both implied volatilities. It is true that with respect to aggregate risk factors, VIX² is the only risk-neutral volatility with some out-of-sample forecasting capacity.

Future research may analyze how the spillover connectedness dynamics reported by González-Urteaga et al. (2018) affect specifically our forecasting results. In other words, given that MOVE is a net sender of volatility to VIX, it would be important to study the consequences of this result for the forecasting ability of these risk-neutral variances. More precisely, it would be interesting to find out what is the percentage of the total predicting capacity of the square of VIX due to the risk-neutral volatility transmission received from MOVE.

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| | VIX | MOVE |
|------------|--------|--------|
| Mean | 0.1949 | 0.0965 |
| Volatility | 0.0731 | 0.0259 |
| Minimum | 0.0951 | 0.0481 |
| Maximum | 0.5989 | 0.2140 |
| Skewness | 1.7367 | 0.9999 |
| Kurtosis | 4.8872 | 2.6046 |
| AR(1) | 0.8405 | 0.8539 |

Table 1. Summary Statistics VIX and MOVE. April 1988-September 2017

The VIX index is the risk-neutral one-month expected stock market volatility for the US S&P500 index. It is computed by averaging the weighted prices of puts and calls on the S&P500 index over a wide range of strike prices. The MOVE index is the Merrill Lynch Option Volatility Estimate Index. It is a term structure weighted index of the normalized implied volatility on one-month Treasury options, which are weighted on the 2, 5, 10, and 30-year contracts. The statistics employ monthly data and observations on the last day of the month.

Table 2. In-Sample Forecasting of Industrial Production Growth for Alternative Horizons with Statistically Significant Controls. Risk-Neutral Variance and its Components, May 1988-June 2017.

| Panel A: Forecastin | ng of Industrial Produc | tion Growth with VIX | X^2 | |
|---|---|--|---|---|
| | h = 1 VIX ² + lagged IPI + Controls | h = 3 VIX ² + lagged IPI + Controls | h = 6 VIX ² + lagged IPI + Controls | h = 12 VIX ² + lagged IPI + Controls |
| \hat{lpha} | 0.013 (4.60) | 0.007 (2.73) | 0.004 (2.63) | 0.004 (2.91) |
| $\hat{\beta}_{l}(VIX^{2})$ | 0.007 (0.05) | -0.016 (-1.54) | 0.000 (0.01) | 0.016 (1.45) |
| Adj R ² | 0.188 | 0.403 | 0.323 | 0.246 |
| | h = 1 $E^{P}(RVAR^{E}) + lagged$ IPI + Controls | h = 3 $E^{P}(RVAR^{E}) + lagged$ IPI + Controls | h = 6 $E^{P}(RVAR^{E}) + lagged$ IPI + Controls | h = 12 $E^{P}(RVAR^{E}) + lagged$ IPI + Controls |
| \hat{lpha} | 0.011 (4.71) | 0.006 (2.38) | 0.003 (2.39) | 0.004 (2.80) |
| $\hat{\beta}_1 E^{P}(RVAR^{E})$ | -0.029 (-2.07) | -0.015 (-1.67) | -0.003 (-0.30) | 0.013 (1.25) |
| Adj R ² | 0.206 | 0.402 | 0.324 | 0.242 |
| | $h = 1$ $VRP^{E} + lagged IPI + Controls$ | h = 3 $VRP^{E} + lagged IPI +$ Controls | $h = 6$ $VRP^{E} + lagged IPI + Controls$ | $h = 12$ $VRP^{E} + lagged IPI +$ $Controls$ |
| \hat{lpha} | 0.012 | 0.008 | 0.003 | 0.004 |
| \hat{eta}_1 (VRP ^E) | -0.035 (-2.31) | -0.000 (-0.03) | -0.004 (-0.57) | -0.001 (-0.32) |
| $Adj R^2$ | 0.211 | 0.392 | 0.324 | 0.229 |
| Panel B: In-Sample | e Forecasting of Indust | rial Production Grow | th with MOVE ² | |
| | h = 1 $MOVE^2 + lagged IPI +$ Controls | h = 3 $MOVE^2 + lagged IPI +$ Controls | h = 6 $MOVE^2 + lagged IPI +$ Controls | h = 12 $MOVE^2 + lagged IPI +$ Controls |
| \hat{lpha} | 0.013 (5.13) | 0.008 (3.23) | 0.004 (3.20) | 0.004 (3.03) |
| $\hat{\beta}_{l}(MOVE^{2})$ | 0.007 (0.08) | -0.031 (-0.56) | -0.061 (-1.05) | -0.009 (-0.16) |
| Adj R ² | 0.187 | 0.393 | 0.328 | 0.229 |
| | h = 1 $E^{P}(RVAR^{T}) + lagged$ IPI + Controls | h = 3 $E^{P}(RVAR^{T}) + lagged$ IPI + Controls | h = 6 $E^{P}(RVAR^{T}) + lagged$ IPI + Controls | h = 12 $E^{P}(RVAR^{T}) + lagged$ IPI + Controls |
| â | 0.013 (4.75) | 0.008 (3.16) | 0.004 (3.05) | 0.003 (2.84) |
| $\hat{\beta}_1 E^{P}(RVAR^T)$ | -0.062 (-0.51) | -0.036 (-0.48) | -0.038 (-0.54) | 0.018 (0.22) |
| | () | (| | (0.22) |
| $Adj R^2$ | 0.189 | 0.393 | 0.324 | 0.230 |
| Adj R ² | 0.189 $h = 1$ $VRP^{T} + lagged IPI + Controls$ | 0.393 $h = 3$ $VRP^{T} + lagged IPI + Controls$ | 0.324 $h = 6$ $VRP^{T} + lagged IPI + Controls$ | 0.230 $h = 12$ $VRP^{T} + lagged IPI + Controls$ |
| Adj R ² | 0.189 $h = 1$ $VRP^{T} + lagged IPI + Controls$ 0.013 (5.06) | 0.393 $h = 3$ $VRP^{T} + lagged IPI + Controls$ 0.008 (3.33) | 0.324 $h = 6$ $VRP^{T} + lagged IPI + Controls$ 0.004 (3.03) | 0.230 $h = 12$ $VRP^{T} + lagged IPI + Controls$ 0.004 (3.07) |
| $\begin{array}{c} Adj R^2 \\ \\ \hat{\alpha} \\ \\ \hat{\beta}_1 (VRP^T) \end{array}$ | 0.189 $h = 1$ $VRP^{T} + lagged IPI + Controls$ 0.013 (5.06) -0.108 (-0.54) | $0.393 \\ h = 3 \\ VRP^{T} + lagged IPI + Controls \\ 0.008 \\ (3.33) \\ 0.016 \\ (0.28) \\ 0.28)$ | 0.324 $h = 6$ $VRP^{T} + lagged IPI + Controls$ 0.004 (3.03) 0.077 (1.60) | 0.230 $h = 12$ $VRP^{T} + lagged IPI + Controls$ 0.004 (3.07) 0.045 (1.1) |

This table shows the results of predicting OLS regressions of future industrial production growth for one-3-, 6-, and 12-month horizons. The predictors are either, VIX², MOVE², the conditional expected realized variance of the S&P500 index or the composite Treasury bond returns, and the variance risk premium (*VRP*) of VIX² or MOVE². We always control for the lagged of the dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound of Nieto and Rubio (2014) and *TED*. We report the *t*-statistic from Newey-West/ HAC standard errors.

| Panel A: Forecastin | ng of Market Excess Ro | eturn with VIX ² | | | | |
|-------------------------------------|--|--|--|---|--|--|
| | h = 1 | h = 3 | h = 6 | h = 12 | | |
| | VIX ² + lagged | | |
| | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | | |
| â | 0.004 | -0.011 | -0.016 | -0.016 | | |
| | (0.87) | (-1.25) | (-2.14) | (-1.72) | | |
| $\hat{eta}_{1}(VIX^{2})$ | 0.051 | 0.089 | 0.131 | 0.088 | | |
| | (0.45) | (0.99) | (2.15) | (2.92) | | |
| Adj R ² | 0.001 | 0.028 | 0.085 | 0.144 | | |
| | h = 1 | h = 3 | h = 6 | h = 12 | | |
| | $E^{P}(RVAR^{E}) + lagged$ | $E^{P}(RVAR^{E}) + lagged$ | $E^{P}(RVAR^{E}) + lagged$ | $E^{P}(RVAR^{E}) + lagged$ | | |
| | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | | |
| â | 0.006 | -0.007 | -0.011 | -0.013 | | |
| | (2.12) | (-0.82) | (-1.64) | (-2.09) | | |
| $\hat{\beta}_1 E^{P}(RVAR^{E})$ | 0.015 | 0.002 | 0.074 | 0.060 | | |
| | (0.19) | (0.03) | (2.08) | (2.81) | | |
| Adj R ² | 0.000 | 0.015 | 0.058 | 0.127 | | |
| | h = 1 | h = 3 | h = 6 | h = 12 | | |
| | $VRP^{E} + lagged$ | $VRP^E + lagged$ | VRP ^E + lagged | VRP ^E + lagged | | |
| | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | | |
| â | 0.005 (2.10) | -0.009 | -0.009 | -0.011 | | |
| \hat{eta}_l (VRP ^E) | -0.065 | -0.123 | -0.045 | -0.016 | | |
| | (-0.52) | (-1.12) | (-0.80) | (-0.49) | | |
| Adj R ² | 0.001 | 0.032 | 0.042 | 0.103 | | |
| Panel B: In-Sample | Forecasting of Marke | t Excess Return with | MOVE ² | | | |
| | h = 1 | h = 3 | h = 6 | h = 12 | | |
| | MOVE ² + lagged | | |
| | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | | |
| â | 0.013 | -0.003 (-0.32) | -0.005 (-0.74) | -0.008 (-1.24) | | |
| \hat{eta}_1 (MOVE ²) | -0.704 | -0.553 | -0.385 | -0.329 | | |
| | (-0.99) | (-1.04) | (-1.09) | (-0.95) | | |
| Adj R ² | 0.072 | 0.028 | 0.049 | 0.115 | | |
| | h = 1 | h = 3 | h = 6 | h = 12 | | |
| | $E^{P}(RVAR^{T}) + lagged$ | $E^{P}(RVAR^{T}) + lagged$ | $E^{P}(RVAR^{T}) + lagged$ | $E^{P}(RVAR^{T}) + lagged$ | | |
| | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | EXCMKT + Controls | | |
| â | 0.008 | -0.004 | -0.006 | -0.008 | | |
| | (1.43) | (-0.43) | (-0.84) | (-1.23) | | |
| $\hat{\beta}_1 E^{P}(RVAR^T)$ | -0.222 | -0.376 | -0.258 | -0.276 | | |
| | (-0.35) | (-0.74) | (-0.63) | (-0.62) | | |
| Adj R ² | 0.000 | 0.019 | 0.042 | 0.108 | | |
| | $h = 1$ $VRP^{T} + lagged$ $EXCMKT + Controls$ | $h = 3$ $VRP^{T} + lagged$ $EXCMKT + Controls$ | $h = 6$ $VRP^{T} + lagged$ $EXCMKT + Controls$ | $h = 12$ $VRP^{T} + lagged$ $EXCMKT + Controls$ | | |
| â | 0.006 | -0.007 | -0.009 | -0.011 | | |
| \hat{eta}_{l} (VRP ^T) | 1.818 (1.57) | 0.808 (1.31) | 0.533 | 0.331 | | |
| $Adj R^2$ | 0.017 | 0.025 | 0.047 | 0.108 | | |

Table 3. In-Sample Forecasting of Excess Market Return for Alternative Horizons with Statistically Significant Controls. Risk-Neutral Variance and its Components, May 1988-June 2017.

This table shows the results of predicting OLS regressions of future stock market excess return for one-, 3-, 6-, and 12-month horizons. The predictors are either, VIX², MOVE², the conditional expected realized variance of the S&P500 index or the composite Treasury bond returns, and the variance risk premium (*VRP*) of VIX² or MOVE². We always control for the lagged of the dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound of Nieto and Rubio (2014) and *TED*. We report the *t*-statistic from Newey-West/ HAC standard errors.

Table 4. In-Sample Forecasting of Excess Treasury Bond Return for Alternative Horizons with Statistically Significant Controls. Risk-Neutral Variance and its Components, May 1988-June 2017.

| r anei A. m-Sample | Forecasting of Excess | s ricasury Dona Retu | | |
|---|--|--|--|---|
| | h = 1 VIX ² + lagged TRYRET + Controls | h = 3 VIX ² + lagged TRYRET + Controls | h = 6 VIX ² + lagged TRYRET + Controls | h = 12 VIX ² + lagged TRYRET + Controls |
| â | -0.001 | 0.001 | 0.002 | 0.002 |
| | (-0.58) | (0.25) | (1.30) | (1.91) |
| $\hat{\beta}_1(VIX^2)$ | 0.056 | 0.029 | 0.000 | 0.008 |
| Adj R ² | 0.075 | 0.001 | 0.019 | 0.162 |
| | h = 1 | h = 3 | h = 6 | h = 12 |
| | $E^{P}(RVAR^{E}) + lagged$ | $E^{P}(RVAR^{E}) + lagged$ | $E^{P}(RVAR^{E}) + lagged$ | $E^{P}(RVAR^{E}) + larged$ |
| | TRYRET + Controls | TRYRET + Controls | TRYRET + Controls | TRYRET + Controls |
| 2 | 0.000 | 0.002 | 0.002 | 0.002 |
| α | (0.03) | (1.18) | (1.89) | (2.83) |
| 2 | 0.046 | 0.001 | -0.015 | -0.003 |
| $\beta_1 E^P(RVAR^E)$ | (0.98) | (0.02) | (-0.99) | (-0.29) |
| 4 <i>l</i> : D ² | 0.000 | 0.001 | 0.022 | 0.1(0) |
| Adj R ² | 0.069 | -0.001 | 0.023 | 0.160 |
| | h = 1 | h = 3 | h = 6 | h = 12 |
| | VRP^E + | VRP^E + | VRP^E + | VRP^E + |
| | lagged TRYRET + | lagged TRYRET + | lagged TRYRET + | lagged TRYRET + |
| | Controls | Controls | Controls | Controls |
| \hat{lpha} | 0.001 | 0.001 | 0.002 | 0.002 |
| | (1.02) | (0.91) | (1.37) | (2.98) |
| $\hat{\beta}_{1}$ (VRP ^E) | -0.008 | -0.057 | -0.035 | -0.023 |
| $P_I(m)$ | (-0.13) | (-2.31) | (-2.54) | (-2.49) |
| $Adj R^2$ | 0.061 | 0.007 | 0.028 | 0.169 |
| Panel B: In-Sample | Forecasting of Excess | s Treasury Bond Retur | rn with MOVE ² | |
| | | • | | |
| | h = 1 | h = 3 | h = 6 | <i>h</i> = <i>12</i> |
| | h = 1 $MOVE^2 +$ | h = 3 $MOVE^2 +$ | $h = 6$ $MOVE^2 +$ | $h = 12$ $MOVE^2 +$ |
| | h = 1 MOVE ² + lagged TRYRET + | h = 3 $MOVE2 + lagged TRYRET +$ | h = 6 MOVE ² + lagged TRYRET + | h = 12 MOVE ² + lagged TRYRET + |
| | h = 1 MOVE ² + lagged TRYRET + Controls | h = 3 MOVE ² + lagged TRYRET + Controls | h = 6 MOVE ² + lagged TRYRET + Controls | h = 12 MOVE ² + lagged TRYRET + Controls |
| â | h = 1 MOVE ² + lagged TRYRET + Controls 0.001 | h = 3 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.000 | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.002 | $h = 12$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.001 |
| â | h = 1 $MOVE2 + $ $lagged TRYRET + $ $Controls$ 0.001 (0.27) | h = 3 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) | h = 6 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) | $h = 12$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.001 (0.99) |
| $\hat{\alpha}$ $\hat{\beta}_{1}(MOVE^{2})$ | h = 1 $MOVE2 + $ $lagged TRYRET + $ $Controls$ 0.001 (0.27) 0.060 0.001 | h = 3 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 | $h = 12$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.001 (0.99) 0.104 |
| \hat{lpha} \hat{eta}_1 (MOVE ²) | | | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) | h = 12 MOVE2 + lagged TRYRET + Controls0.001(0.99)0.104(1.08) |
| \hat{lpha} \hat{eta}_1 (MOVE ²) Adj R ² | | | | h = 12 MOVE2 + lagged TRYRET + Controls0.001 (0.99) 0.104 (1.08) 0.168 |
| \hat{lpha} \hat{eta}_1 (MOVE ²) Adj R ² | | | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ | h = 12 MOVE2 + lagged TRYRET + Controls 0.001 (0.99) 0.104 (1.08) 0.168 h = 12 |
| \hat{lpha} \hat{eta}_1 (MOVE ²) Adj R ² | $ \begin{array}{c} h = 1 \\ MOVE^2 + \\ lagged \ TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h = 1 \\ E^p(RVAR^T) + lagged \end{array} $ | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{p}(RVAR^{T}) + lagged$ | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ $E^{p}(RVAR^{T}) + lagged$ | $h = 12$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.001 (0.99) 0.104 (1.08) 0.168 $h = 12$ $E^{p}(RVAR^{T}) + lagged$ |
| \hat{lpha} \hat{eta}_1 (MOVE ²) Adj R ² | $\begin{array}{c} h = 1\\ MOVE^2 +\\ lagged\ TRYRET +\\ Controls\\ \hline 0.001\\ (0.27)\\ 0.060\\ (0.22)\\ 0.064\\ \hline h = 1\\ E^p(RVAR^T) + lagged\\ TRYRET + Controls\\ \end{array}$ | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ | h = 6 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ $EP(RVART) + lagged$ $TRYRET + Controls$ | h = 12 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.001 (0.99) 0.104 (1.08) 0.168 $h = 12$ $EP(RVART) + lagged$ $TRYRET + Controls$ |
| $\hat{\alpha}$ $\hat{\beta}_1 (MOVE^2)$ $Adj R^2$ | $\begin{array}{c} h = 1\\ MOVE^2 +\\ lagged \ TRYRET +\\ Controls\\ \hline 0.001\\ (0.27)\\ 0.060\\ (0.22)\\ \hline 0.064\\ \hline h = 1\\ E^p(RVAR^T) + lagged\\ TRYRET + Controls\\ \hline -0.002\\ \end{array}$ | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.001 | h = 6 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ $EP(RVART) + lagged$ $TRYRET + Controls$ 0.002 | h = 12 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.001 (0.99) 0.104 (1.08) 0.168 $h = 12$ $EP(RVART) + lagged$ $TRYRET + Controls$ 0.001 |
| \hat{lpha} \hat{eta}_1 (MOVE ²) Adj R ² \hat{lpha} | $\begin{array}{c} h = 1\\ MOVE^2 +\\ lagged \ TRYRET +\\ Controls\\ \hline 0.001\\ (0.27)\\ 0.060\\ (0.22)\\ 0.064\\ \hline h = 1\\ E^p(RVAR^T) + lagged\\ TRYRET + Controls\\ \hline -0.002\\ (-0.80)\\ \end{array}$ | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.001 (0.42) | h = 6 $MOVE2 +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ $EP(RVART) + lagged$ $TRYRET + Controls$ 0.002 (1.06) | h = 12 MOVE2 + lagged TRYRET + Controls 0.001 (0.99) 0.104 (1.08) 0.168 $h = 12 Ep(RVART) + lagged TRYRET + Controls 0.001 (0.82)$ |
| $\hat{\alpha}$ $\hat{\beta}_1 (MOVE^2)$ $Adj R^2$ $\hat{\alpha}$ $\hat{\alpha}$ | | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ \hline Controls \\ 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ 0.001 \\ (0.82) \\ 0.096 \\ \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1}(MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ | | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.001 (0.42) 0.060 (0.26) | | h = 12 MOVE2 + lagged TRYRET + Controls 0.001 (0.99) 0.104 (1.08) 0.168 $h = 12 Ep(RVART) + lagged TRYRET + Controls 0.001 (0.82) 0.096 (0.74)$ |
| $\hat{\alpha}$ $\hat{\beta}_{1}(MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{p}(RVAR^{T})$ $Adj R^{2}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h &= 1 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \end{split} $ | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.001 (0.42) 0.060 (0.26) -0.005 | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.002 (1.06) -0.034 (-0.19) 0.019 | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1}(MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ | $ \begin{array}{c} h = 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h = 1 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h = 1 \end{array} $ | $h = 3$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.000 (0.02) 0.169 (0.76) -0.001 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.001 (0.42) 0.060 (0.26) -0.005 $h = 3$ | $h = 6$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.002 (0.97) 0.025 (0.18) 0.019 $h = 6$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.002 (1.06) -0.034 (-0.19) 0.019 $h = 6$ | $h = 12$ $MOVE^{2} +$ $lagged TRYRET +$ $Controls$ 0.001 (0.99) 0.104 (1.08) 0.168 $h = 12$ $E^{P}(RVAR^{T}) + lagged$ $TRYRET + Controls$ 0.001 (0.82) 0.096 (0.74) 0.165 $h = 12$ |
| $\hat{\alpha}$ $\hat{\beta}_{1}(MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \end{split} $ $ \begin{split} h &= 1 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \cr h &= 1 \\ VRP^T + \end{split} $ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \hline h = 12 \\ VRP^T + \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1} (MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h &= 1 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h &= 1 \\ VRP^T + \\ lagged TRYRET + \end{split} $ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \end{array}$ $\begin{array}{c} h = 12 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \end{array}$ $\begin{array}{c} h = 12 \\ VRP^T + \\ lagged TRYRET + \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1} (MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h &= 1 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h &= 1 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ \end{split} $ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \end{array}$ $\begin{array}{c} h = 12 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \end{array}$ $\begin{array}{c} h = 12 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1} (MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ $\hat{\alpha}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \end{split} \\ h &= 1 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h &= 1 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ \end{split}$ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \hline h = 12 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ 0.002 \\ \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1} (MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ $\hat{\alpha}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h &= 1 \\ E^P(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h &= 1 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (1.14) \\ \end{split} $ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \hline h = 12 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ 0.002 \\ (3.42) \\ \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1} (MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\alpha}$ $\hat{\alpha}$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \hline h &= 1 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h &= 1 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (1.14) \\ 0.582 \\ \end{split} $ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \hline h = 12 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ \hline 0.002 \\ (3.42) \\ -0.123 \\ \end{array}$ |
| $\hat{\alpha}$ $\hat{\beta}_{1}(MOVE^{2})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} (VRP^{T})$ | $ \begin{split} h &= 1 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ 0.001 \\ (0.27) \\ 0.060 \\ (0.22) \\ 0.064 \\ \end{split} \\ h &= 1 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline -0.002 \\ (-0.80) \\ 0.368 \\ (1.31) \\ 0.068 \\ \hline h &= 1 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (1.14) \\ 0.582 \\ (1.20) \\ \end{split}$ | | | $\begin{array}{c} h = 12 \\ MOVE^2 + \\ lagged TRYRET + \\ Controls \\ \hline 0.001 \\ (0.99) \\ 0.104 \\ (1.08) \\ 0.168 \\ \hline h = 12 \\ E^p(RVAR^T) + lagged \\ TRYRET + Controls \\ \hline 0.001 \\ (0.82) \\ 0.096 \\ (0.74) \\ 0.165 \\ \hline h = 12 \\ VRP^T + \\ lagged TRYRET + \\ Controls \\ \hline 0.002 \\ (3.42) \\ -0.123 \\ (-1.54) \\ \end{array}$ |

This table shows the results of predicting OLS regressions of future Treasury bond excess return for one-3-, 6-, and 12-month horizons. The predictors are either, VIX², MOVE², the conditional expected realized variance of the S&P500 index or the composite Treasury bond returns, and the variance risk premium (*VRP*) of VIX² or MOVE². We always control for the lagged of the dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound of Nieto and Rubio (2014) and *TED*. We report the *t*-statistic from Newey-West/ HAC standard errors.

| | - | | | | | |
|---|---|--|--|--|--|--|
| | h = 1 VIX ² + lagged HML + Controls | h = 3 VIX ² + lagged HML + Controls | $h = 6$ $VIX^{2} + lagged HML + Controls$ | $h = 12$ $VIX^{2} + lagged HML +$ Controls | | |
| \hat{lpha} | 0.018 (2.62) | 0.006 (2.73) | 0.018 (2.64) | 0.013 (2.49) | | |
| $\hat{eta}_{l}(VIX^2)$ | -0.107 (-2.70) | -0.110 (-2.34) | -0.046 (-1.32) | -0.023 (-0.99) | | |
| $Adj R^2$ | 0.051 | 0.060 | 0.054 | 0.039 | | |
| | h = 1 $E^{P}(RVAR^{E}) + lagged$ HML + Controls | h = 3 $E^{P}(RVAR^{E}) + lagged$ HML + Controls | h = 6 $E^{P}(RVAR^{E}) + lagged$ HML + Controls | h = 12 $E^{P}(RVAR^{E}) + lagged$ HML + Controls | | |
| \hat{lpha} | 0.016 (2.29) | 0.005 (2.35) | 0.016 (2.41) | 0.013 (2.33) | | |
| $\hat{\beta}_1 E^{P}(RVAR^{E})$ | -0.076 (-2.08) | -0.092 (-2.31) | -0.018 (-0.79) | 0.001 (0.04) | | |
| $Adj R^2$ | 0.042 | 0.052 | 0.041 | 0.031 | | |
| | $h = 1$ $VRP^{E} + lagged HML + Controls$ | h = 3 $VRP^{E} + lagged HML +$ <i>Controls</i> | $h = 6$ $VRP^{E} + lagged HML + Controls$ | h = 12 $VRP^{E} + lagged HML +$ <i>Controls</i> | | |
| \hat{lpha} | 0.015 (2.16) | 0.002 (0.78) | 0.017 (2.47) | 0.013 (2.49) | | |
| \hat{eta}_1 (VRP ^E) | 0.039 (0.32) | 0.001 (0.01) | 0.048 (0.94) | 0.048 (1.61) | | |
| Adj R ² | 0.031 | 0.009 | 0.047 | 0.047 | | |
| Panel B: In-Sample | e Forecasting of HML | with MOVE ² | | | | |
| | h = 1 $MOVE^2 + lagged HML$ + Controls | h = 3 $MOVE^2 + lagged HML$ + Controls | h = 6 $MOVE^2 + lagged HML$ + Controls | h = 12 $MOVE^2 + lagged HML$ + Controls | | |
| \hat{lpha} | 0.020 (2.53) | 0.006 | 0.018 | 0.013 | | |
| $\hat{\beta}_1(MOVE^2)$ | | (1.50) | (2.46) | (2.37) | | |
| / 1 (| -0.517 (-1.63) | -0.432 (-1.06) | -0.179 (-0.77) | (2.37) -0.038 (-0.30) | | |
| $Adj R^2$ | -0.517 (-1.63) 0.041 | -0.432 (-1.06) 0.027 | (2.46) -0.179 (-0.77) 0.043 | (2.37) -0.038 (-0.30) 0.032 | | |
| Adj R ² | -0.517 (-1.63) 0.041 $h = 1$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ | (1.36) -0.432 (-1.06) 0.027 $h = 3$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ | (2.46) -0.179 (-0.77) 0.043 $h = 6$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ | $(2.37) -0.038 (-0.30) 0.032 h = 12 E^{P}(RVAR^{T}) + lagged HML + Controls$ | | |
| $\hat{A}dj R^2$ $\hat{\alpha}$ | $\begin{array}{c} -0.517\\(-1.63)\\ \hline 0.041\\ \hline h=1\\ E^{P}(RVAR^{T})+lagged\\ \underline{HML+Controls}\\ \hline 0.018\\(1.73)\end{array}$ | $(1.36) -0.432 (-1.06) 0.027 h = 3 E^{P}(RVAR^{T}) + lagged HML + Controls 0.005 (1.04)$ | $(2.46) -0.179 (-0.77) 0.043$ $h = 6$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ $0.016 (2.05)$ | $(2.37) -0.038 (-0.30) 0.032 h = 12 E^{P}(RVAR^{T}) + lagged HML + Controls 0.013 (2.19) $ | | |
| $\hat{A} dj R^2$ $\hat{\alpha}$ $\hat{\beta}_1 E^p(RVAR^T)$ | $\begin{array}{c} -0.517 \\ (-1.63) \\ \hline 0.041 \\ \hline h = 1 \\ E^{P}(RVAR^{T}) + lagged \\ \underline{HML + Controls} \\ \hline 0.018 \\ (1.73) \\ -0.270 \\ (-0.51) \\ \end{array}$ | $(1.36) -0.432 \\ (-1.06) \\ 0.027 \\ h = 3 \\ E^{P}(RVAR^{T}) + lagged \\ HML + Controls \\ 0.005 \\ (1.04) \\ -0.369 \\ (-0.76) \\ (-0.76) \\ (1.04) \\ -0.369 \\ (-0.76) \\ (-0.$ | $(2.46) -0.179 (-0.77) 0.043$ $h = 6$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ $0.016 (2.05) -0.018 (-0.07)$ | $(2.37) -0.038 (-0.30) 0.032 h = I2 E^{P}(RVAR^{T}) + lagged HML + Controls 0.013 (2.19) -0.001 (-0.04) (2.37) (2.37) (2.37) (2.37) (2.37) (-0.38) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.30) (-0.32) (-0.33) (-0.32) (-0.33) (-0.34) (-0.34) (-0.34) (-0.04) (-0.04) (-0.04) (-0.04) (-0.04) (-0.04) (-0.35) (-0.35) (-0.04) (-0.04) (-0.04) (-0.04) (-0.35) (-0.35) (-0.35) (-0.35) (-0.35) (-0.04) (-0$ | | |
| $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ | $-0.517 \\ (-1.63) \\ 0.041 \\ \hline h = 1 \\ E^{P}(RVAR^{T}) + lagged \\ HML + Controls \\ 0.018 \\ (1.73) \\ -0.270 \\ (-0.51) \\ 0.032 \\ \hline \end{tabular}$ | (1.36) -0.432 (-1.06) 0.027 h = 3 EP(RVART) + lagged HML + Controls 0.005 (1.04) -0.369 (-0.76) 0.018 0.018 | $(2.46) -0.179 (-0.77) 0.043$ $h = 6$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ $0.016 (2.05) -0.018 (-0.07) 0.038$ | $(2.37) -0.038 (-0.30) 0.032 h = 12 E^{P}(RVAR^{T}) + lagged HML + Controls 0.013 (2.19) -0.001 (-0.04) 0.031 (2.01) 0.031 (2.13) (2.14) (2.15) (2.15) (-0.01) (-0.04) (-0.03) (-0.03) (-0.03) (-0.03) (-0.03) (-0.04) (-0.03) (-0.04)$ | | |
| $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ | $\begin{array}{c} -0.517 \\ (-1.63) \\ 0.041 \\ \hline h = 1 \\ E^{P}(RVAR^{T}) + lagged \\ HML + Controls \\ 0.018 \\ (1.73) \\ -0.270 \\ (-0.51) \\ 0.032 \\ \hline h = 1 \\ VRP^{T} + lagged HML + \\ Controls \end{array}$ | (1.36) -0.432 (-1.06) 0.027 h = 3 EP(RVART) + lagged HML + Controls 0.005 (1.04) -0.369 (-0.76) 0.018 h = 3 VRPT + lagged HML + Controls | $(2.46) -0.179 (-0.77) 0.043$ $h = 6 E^{P}(RVAR^{T}) + lagged HML + Controls 0.016 (2.05) -0.018 (-0.07) 0.038$ $h = 6 VRP^{T} + lagged HML + Controls$ | (2.37) -0.038 (-0.30) 0.032 h = 12 EP(RVART) + lagged HML + Controls 0.013 (2.19) -0.001 (-0.04) 0.031 h = 12 VRPT + lagged HML + Controls | | |
| $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\alpha}$ | $\begin{array}{c} -0.517 \\ (-1.63) \\ \hline 0.041 \\ \hline h = 1 \\ E^{P}(RVAR^{T}) + lagged \\ \hline HML + Controls \\ \hline 0.018 \\ (1.73) \\ -0.270 \\ (-0.51) \\ \hline 0.032 \\ \hline h = 1 \\ VRP^{T} + lagged HML + \\ \hline Controls \\ \hline 0.013 \\ (1.82) \end{array}$ | $(1.36) -0.432 (-1.06) 0.027 h = 3 E^{P}(RVAR^{T}) + lagged HML + Controls 0.005 (1.04) -0.369 (-0.76) 0.018 h = 3 VRP^{T} + lagged HML + Controls 0.001 (0.79)$ | $(2.46) -0.179 (-0.77) 0.043 h = 6 E^{P}(RVAR^{T}) + lagged HML + Controls 0.016 (2.05) -0.018 (-0.07) 0.038 h = 6 VRP^{T} + lagged HML + Controls 0.015 (2.34)$ | (2.37) -0.038 (-0.30) 0.032 h = 12 EP(RVART) + lagged HML + Controls 0.013 (2.19) -0.001 (-0.04) 0.031 h = 12 VRPT + lagged HML + Controls 0.012 (2.19) | | |
| $\hat{\alpha}$ $\hat{\beta}_{1} E^{P}(RVAR^{T})$ $Adj R^{2}$ $\hat{\alpha}$ $\hat{\beta}_{1} (VRP^{T})$ | $-0.517 \\ (-1.63) \\ 0.041 \\ \hline h = 1 \\ E^{P}(RVAR^{T}) + lagged \\ HML + Controls \\ 0.018 \\ (1.73) \\ -0.270 \\ (-0.51) \\ 0.032 \\ \hline h = 1 \\ VRP^{T} + lagged HML + \\ Controls \\ 0.013 \\ (1.82) \\ 1.128 \\ (2.84) \\ \hline \end{pmatrix}$ | (1.36) -0.432 (-1.06) 0.027 h = 3 EP(RVART) + lagged HML + Controls 0.005 (1.04) -0.369 (-0.76) 0.018 h = 3 VRPT + lagged HML + Controls 0.001 (0.79) 0.611 (1.52) | (2.46) -0.179 (-0.77) 0.043 h = 6 EP(RVART) + lagged HML + Controls 0.016 (2.05) -0.018 (-0.07) 0.038 h = 6 VRPT + lagged HML + Controls 0.015 (2.34) 0.537 (2.32) | (2.37) -0.038 (-0.30) 0.032 $h = 12$ $E^{P}(RVAR^{T}) + lagged$ $HML + Controls$ 0.013 (2.19) -0.001 (-0.04) 0.031 $h = 12$ $VRP^{T} + lagged HML + Controls$ 0.012 (2.19) 0.012 (2.19) 0.108 (0.91) | | |

Table 5. In-Sample Forecasting of *HML* for Alternative Horizons with Statistically Significant Controls. Risk-Neutral Variance and its Components, May 1988-June 2017.

This table shows the results of predicting OLS regressions of future *HML* return for one, -3-, 6-, and 12month horizons. The predictors are either, VIX², MOVE², the conditional expected realized variance of the S&P500 index or the composite Treasury bond returns, and the variance risk premium (*VRP*) of VIX² or MOVE². We always control for the lagged of the dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound of Nieto and Rubio (2014) and *TED*. We report the *t*-statistic from Newey-West/ HAC standard errors.

Table 6. In-Sample Forecasting of *BAB* for Alternative Horizons with Statistically Significant Controls. Risk-Neutral Variance and its Components, May 1988-June 2017.

| | c Porceasting of DAD v | | | |
|---------------------------------|----------------------------|----------------------------|----------------------------|----------------------------|
| | h=1 | h = 3 | h = 6 | h = 12 |
| | $VIX^2 + lagged BAB +$ |
| | Controls | Controls | Controls | Controls |
| â | 0.046 | 0.041 | 0.048 | 0.030 |
| u | (4.68) | (4.07) | (4.39) | (2.70) |
| ô (mm) | -0.221 | -0.134 | -0.077 | -0.058 |
| $\beta_1(VIX^2)$ | (-3.25) | (-1.74) | (-1.37) | (-1.28) |
| | | · · · | | |
| $Adj R^2$ | 0.109 | 0.173 | 0.219 | 0.295 |
| | h = 1 | h-3 | h-6 | h - 12 |
| | $F^{P}(RVAR^{E}) + lagged$ | $F^{P}(RVAR^{E}) + lagged$ | $F^{P}(RVAR^{E}) + lagged$ | $F^{P}(RVAR^{E}) + lagged$ |
| | BAB + Controls | BAB + Controls | BAB + Controls | BAB + Controls |
| | 0.039 | 0.036 | 0.037 | 0.027 |
| \hat{lpha} | (4 13) | (3.79) | (3.99) | (2.48) |
| ^ | 0.044 | (5.77) | 0.005 | 0.013 |
| $\beta_1 E^P(RVAR^E)$ | -0.044 | -0.012 | (0.11) | -0.013 |
| | (-0.55) | (-0.18) | (0.11) | (-0.38) |
| $Adj R^2$ | 0.061 | 0.129 | 0.196 | 0.278 |
| | h = 1 | $h = \beta$ | h = 6 | h = 12 |
| | $VRP^E + lagged BAB +$ |
| | Controls | Controls | Controls | Controls |
| | 0.042 | 0.038 | 0.039 | 0.028 |
| α | (4.65) | (4.07) | (4.31) | (2.62) |
| 2 | 0.310 | 0.217 | 0 149 | 0.072 |
| $\beta_1 (VRP^E)$ | (3.14) | (3.76) | (3.72) | (1.90) |
| | (5.14) | (5.76) | (5.72) | (1.90) |
| Adj R ² | 0.113 | 0.192 | 0.243 | 0.293 |
| Panel B: In-Sample | e Forecasting of BAB w | with MOVE ² | | |
| | h = 1 | h = 3 | h = 6 | h = 12 |
| | $MOVE^2 + lagged BAB$ |
| | + Controls | + Controls | + Controls | + Controls |
| â | 0.044 | 0.040 | 0.038 | 0.028 |
| α | (4.59) | (4.24) | (4.29) | (2.47) |
| â | -0.508 | -0.339 | -0.044 | -0.088 |
| $\beta_1(MOVE^2)$ | (-1.27) | (-1.03) | (-0.15) | (-0.33) |
| | | | | |
| $Adj R^2$ | 0.064 | 0.135 | 0.196 | 0.278 |
| | h = 1 | h = 3 | h = 6 | h = 12 |
| | $E^{P}(RVAR^{T}) + lagged$ | $E^{P}(RVAR^{T}) + lagged$ | $E^{P}(RVAR^{T}) + lagged$ | $E^{P}(RVAR^{T}) + lagged$ |
| | BAB + Controls | BAB + Controls | BAB + Controls | BAB + Controls |
| â | 0.041 | 0.036 | 0.036 | 0.027 |
| CC . | (4.23) | (3.94) | (3.92) | (2.43) |
| $\hat{B}_{I} = F^{P}(PVAP^{T})$ | -0.287 | -0.022 | 0.098 | -0.076 |
| $p_I = (KVAK)$ | (-0.56) | (-0.06) | (0.25) | (-0.24) |
| $Adj R^2$ | 0.060 | 0.129 | 0.199 | 0.277 |
| | h = 1 | h = 3 | h = 6 | <i>h</i> = <i>12</i> |
| | $VRP^{T} + lagged BAB +$ |
| | Controls | Controls | Controls | Controls |
| ~ | 0.038 | 0.035 | 0.037 | 0.027 |
| α | (3.97) | (3.74) | (3.99) | (2.45) |
| 2 | 0.838 | 0.878 | 0.299 | 0.094 |
| $\beta_1 (VRP^T)$ | (1.16) | (2.54) | (1.09) | (0.38) |
| $Adj R^2$ | 0.064 | 0.143 | 0.199 | 0.277 |
| | | | | |

Panel A: In-Sample Forecasting of BAB with VIX²

This table shows the results of predicting OLS regressions of future *BAB* return for one, -3-, 6-, and 12month horizons. The predictors are either, VIX², MOVE², the conditional expected realized variance of the S&P500 index or the composite Treasury bond returns, and the variance risk premium (*VRP*) of VIX² or MOVE². We always control for the lagged of the dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound of Nieto and Rubio (2014) and *TED*. We report the *t*-statistic from Newey-West/ HAC standard errors.

| | Panel A: Out-of-Sample Forecasting of Industrial Production Growth | | | | | | | | | |
|--------------------|--|---|---|---|---|---|---|---|--|--|
| | h = | = 1 | h = | = 3 | h = | = 6 | h = | 12 | | |
| | VIX ² | MOVE ² | VIX ² | MOVE ² | VIX ² | MOVE ² | VIX ² | MOVE ² | | |
| | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | | |
| RMSE | 0.987 | 1.005 | 0.966 | 0.997 | 0.996 | 0.990 | 1.013 | 1.001 | | |
| p-value (t) | 0.322 | 0.749 | 0.004 | 0.030 | 0.023 | 0.016 | 0.095 | 0.040 | | |
| value (F) | 0.291 | 0.701 | 0.000 | 0.015 | 0.005 | 0.003 | 0.856 | 0.057 | | |
| Result | NO | NO NO YES YES YES NO | | NO | NO | | | | | |
| | Panel B: Out-of-Sample Forecasting of Stock Market Excess Return | | | | | | | | | |
| | h = | = 1 | h = | = 3 | h = | = 6 | h = | = 12 | | |
| | VIX ² improves MOVE ² | MOVE ² improves VIX ² | VIX ² improves MOVE ² | MOVE ² improves VIX ² | VIX ² improves MOVE ² | MOVE ² improves VIX ² | VIX ² improves MOVE ² | MOVE ² improves VIX ² | | |
| RMSE | 1.002 | 0.997 | 0.997 | 0.989 | 0.977 | 0.983 | 0.986 | 0.994 | | |
| p- value (t) | 0.277 | 0.064 | 0.064 | 0.006 | 0.005 | 0.001 | 0.003 | 0.023 | | |
| p- value (F) | 0.250 | 0.073 | 0.051 | 0.002 | 0.003 | 0.000 | 0.000 | 0.005 | | |
| Result | NO | YES | | |
| | Pa | nel C: Out-c | of-Sample Fo | recasting of | Treasury Bo | ond Excess R | eturn | | | |
| | h = | = 1 | h = | = 3 | h = | = 6 | h = | = 12 | | |
| | VIX ² | MOVE ² | VIX ² | MOVE ² | VIX ² | MOVE ² | VIX ² | MOVE ² | | |
| | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | | |
| RMSE | 0.993 | 1.004 | 1.004 | 1.005 | 1.005 | 1.007 | 1.034 | 0.995 | | |
| p- value (t) | 0.047 | 0.444 | 0.100 | 0.331 | 0.147 | 0.271 | 0.248 | 0.018 | | |
| p- value (F) | 0.030 | 0.513 | 0.291 | 0.463 | 0.384 | 0.612 | 0.999 | 0.006 | | |
| Result | YES | NO | NO | NO | NO | NO | NO | YES | | |

Table 7. Out-of-Sample Forecasting Performance of VIX² and MOVE², May 1988-June 2017.

| | | Pa | nel D: Out-of | -Sample Fore | casting of HN | ЛL | | |
|---|---|---|--|---|--|---|--|---|
| | h = | = 1 | h = | = 3 | h = | = 6 | h = | 12 |
| | VIX ² improves MOVE ² | MOVE ² improves VIX ² | VIX ² improves MOVE ² | MOVE ² improves VIX ² | VIX ² improves MOVE ² | MOVE ² improves VIX ² | VIX ² improves MOVE ² | MOVE ² improves VIX ² |
| RMSE | 1.005 | 1.005 | 0.990 | 1.004 | 1.012 | 1.012 1.008 | | 1.003 |
| <i>p</i> -value (<i>t</i>) | 0.846 | 0.846 0.851 | | 0.024 0.197 | | 0.624 | 0.095 | 0.123 |
| <i>p</i> -value (<i>F</i>) | 0.722 | 0.722 0.728 | | 0.445 | 0.758 | 0.704 | 0.963 | 0.142 |
| Result | NO | NO | YES NO NO NO | | | | NO | NO |
| | | Pa | nel E: Out-of | | | | | |
| | <i>h</i> = | = 1 | h = | = 3 | <i>h</i> = | = 6 | h = | 12 |
| | VIX ² MOVE ² improves improves MOVE ² VIX ² | | 2 ² VIX ² MOVI es improves improv MOVE ² VIX ² | | VIX^2 | $MOVE^2$ | VIX ² | MOVE ² |
| | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² | improves MOVE ² | improves VIX ² |
| RMSE | improves MOVE ² 0.989 | improves VIX ² 1.003 | improves MOVE ² 1.021 | improves VIX ² 1.005 | improves MOVE ² 1.010 | improves VIX ² 1.004 | improves MOVE ² | improves VIX ² 1.002 |
| <i>RMSE</i> <i>p</i> -value (<i>t</i>) | improves MOVE ² 0.989 0.160 | improves VIX ² 1.003 0.911 | improves MOVE ² 1.021 0.144 | improves VIX ² 1.005 0.113 | improves <u>MOVE²</u> 1.010 0.032 | improves VIX ² 1.004 0.107 | improves <u>MOVE²</u> 0.922 0.013 | improves VIX ² 1.002 0.041 |
| <i>RMSE</i> <i>p</i> -value (<i>t</i>) <i>p</i> -value (<i>F</i>) | improves MOVE ² 0.989 0.160 0.053 | improves VIX ² 1.003 0.911 0.856 | improves MOVE ² 1.021 0.144 0.991 | improves VIX ² 1.005 0.113 0.261 | improves <u>MOVE²</u> 1.010 0.032 0.758 | improves VIX ² 1.004 0.107 0.266 | improves <u>MOVE²</u> 0.922 0.013 0.000 | improves VIX ² 1.002 0.041 0.101 |

Table 7 (continuation). Out-of-Sample Forecasting Performance of VIX² and MOVE², May 1988-June 2017.

This table shows the out-of-sample forecast accuracy of either VIX² or MOVE², comparing the unrestricted model that contains either VIX² or MOVE² and the additional standard predictor with the restricted model that includes only the standard predictor where this predictor can also be VIX² or MOVE². *RMSE* is the relative mean-squared forecasting error that compares the mean-squared forecasting error of the restricted model and the mean-squared forecasting error of the unrestricted model. The *p*-value (*t*) and *p*-value (*F*) are two statistics to test the equal forecasting ability of the two models associated with expressions (28) and (30). They are obtained by an efficient bootstrap method for simulating asymptotic critical values.

















APPENDIX: Out-of-Sample Competing Performance of VIX² and MOVE²

In Tables A.1 to A.5 shown below, we report the detailed results discussed in the outof-sample analysis of Section 5 of the paper. All tables have the same structure. For each horizon, we present the in-sample and out-of-sample results for the same competing predictors. In the first panel, for a given horizon, we show the in-sample evidence with a regression of two independent variables, namely each of the competing predictors and either VIX² or MOVE². In the second panel, again for a given horizon, we report the pairwise out-of-sample forecasting comparison. This is to say, we compare either VIX² or MOVE² against each of the competitors and report the *RMSE* and the corresponding *p*-values.

With respect to the forecasting of real activity reported in Table A.1, *DEF*, *HJ* volatility bound and *TED* are all significant predictors with a negative sign at the short horizons. At longer horizons, *TERM* becomes a significant predictor with a positive sign, but the *HJ* bound and *TED* remain significantly different from zero. Except for *TED*, all results have been found before in literature. In Table A.2, we show that only *TERM* and *DY* predict future excess market returns at longer horizons and with the expected positive sign. Table A.3 contains the results regarding Treasury excess returns. *DEF* is a significant predictor for all horizon. The results about *HML* are displayed in Table A.4. *DEF* with a positive sign, and the *HJ* bound with a negative sign are significant predictors of the value-growth risk-factor at all horizons and, finally, Table A.5 shows that the *HJ* volatility bound with a negative sign and *TERM* with a positive sign are significant predictor of the BAB factor at practically all horizons.

| | | | | Pan | el A: In | -Sample | e Foreca | sting A | bility: τ | = 1 | | | | |
|----------------------------|-------------------|-------------------|-------------------------|------------------------------|-----------------------------|---------------------------|--------------------------|---|---------------------|-------------------------|-------------------------|--|------------------------------|----------------------------|
| | Δl | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $T_t + \beta_2 V I_t$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | | $\Delta IPI_{t,t+}$ | $\tau = \alpha + \mu$ | $\beta_l X_t + \beta_l$ | $_2MOVE_t^2$ | $2 + \varepsilon_{t,t+\tau}$ | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.003 (5.42) | 0.003 (3.08) | 0.008 (5.16) | 0.006 (3.67) | 0.008 (3.71) | 0.004 (4.26) | 0.004 (6.29) | 0.003 (3.12) | 0.003 (2.38) | 0.009 (5.22) | 0.005 (2.71) | 0.009 (3.30) | 0.004 (4.26) | 0.004 (3.79) |
| $\hat{\beta}_l$ | 0.162 (2.36) | 0.036 (1.15) | -0.287 (-3.41) | -0.112 (-1.77) | -0.008 (-2.20) | -0.067 (-0.68) | -0.162 (-2.38) | 0.171 (2.27) | 0.059 (2.05) | -0.303 (-4.11) | -0.076 (-1.12) | -0.009 (-2.31) | -0.040 (-2.43) | -0.186 (-2.48) |
| $\hat{\beta}_2$ | -0.041 (-3.06) | -0.047 (-2.79) | -0.010 (-0.79) | -0.046 (-3.24) | -0.045 (-3.18) | -0.040 (-2.43) | -0.040 (-2.74) | -0.190 (-1.78) | -0.262 (-2.13) | -0.051 (-0.67) | -0.221 (-1.85) | -0.235 (-2.16) | -0.067 (-0.68) | -0.189 (-1.70) |
| Adj R ² | 0.101 | 0.085 | 0.151 | 0.095 | 0.102 | 0.083 | 0.097 | 0.072 | 0.057 | 0.150 | 0.051 | 0.072 | 0.083 | 0.066 |
| | | | | Panel A | 4.1: Out | t-of-San | nple For | ecasting | g Ability | $\tau : \tau = 1$ | | | | |
| | Unr | estricted | : $\Delta IPI_{t,t+}$ | $a_{\tau} = \alpha + \beta$ | $\beta_l X_t + \beta_2$ | $VIX_t^2 + \varepsilon_t$ | <i>t</i> , <i>t</i> +τ | Unrestricted : $\Delta IPI_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | |
| | Res | stricted : 2 | $\Delta IPI_{t,t+\tau}$ | $= \alpha + \beta_l \lambda$ | $X_t + \varepsilon_{t,t+1}$ | τ | | Re stri | cted : ΔI | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $t_t + \varepsilon_{t,t+\tau}$ | - | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 0.977 | 0.964 | 1,013 | 0.960 | 0.967 | 0.987 | 0.979 | 0.996 | 0.979 | 1.012 | 0.988 | 0.988 | 1.005 | 0.995 |
| <i>p</i> -val (<i>t</i>) | 0.018 | 0.043 | 0.994 | 0.025 | 0.507 | 0.322 | 0.054 | 0.138 | 0.106 | 0.959 | 0.122 | 0.576 | 0.749 | 0.233 |
| p-val (F) | 0.003 | 0.005 | 0.980 | 0.001 | 0.326 | 0.291 | 0.026 | 0.123 | 0.037 | 0.916 | 0.070 | 0.531 | 0.701 | 0.213 |
| | | | | Pan | el B: In | -Sample | e Foreca | sting Al | bility: $	au$ | = 3 | | | | |
| | Δl | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $f_t + \beta_2 V I_t$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | $\Delta IPI_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.002 (3.98) | 0.003 (3.43) | 0.007 (4.61) | 0.006 (3.97) | 0.008 (3.63) | 0.004 (4.74) | 0.004 (7.66) | 0.002 (2.65) | 0.003 (2.55) | 0.008 (4.80) | 0.005 (2.83) | 0.009 (3.34) | 0.004 (4.74) | 0.004 (4.25) |
| $\hat{\beta}_{I}$ | 0.455 (4.54) | 0.045 (1.60) | -0.181 (-2.37) | -0.092 (-1.62) | -0.008 (-2.16) | -0.094 (-0.86) | -0.179 (-2.42) | 0.504 (6.14) | 0.072 (2.68) | -0.226 (-4.09) | -0.048 (-0.76) | -0.009 (-2.43) | -0.042 (-2.90) | -0.200 (-2.52) |
| $\hat{\beta}_2$ | -0.028 (-3.38) | -0.050 (-3.20) | -0.027 (-1.83) | -0.050 (-3.70) | -0.048 (-3.79) | -0.042 (-2.90) | -0.044 (-3.80) | -0.107 (-1.39) | -0.300 (-2.33) | -0.130 (-1.37) | -0.261 (-2.00) | -0.266 (-2.41) | -0.094 (-0.86) | -0.216 (-2.14) |
| Adj R ² | 0.365 | 0.213 | 0.255 | 0.217 | 0.245 | 0.208 | 0.236 | 0.331 | 0.161 | 0.244 | 0.130 | 0.183 | 0.208 | 0.169 |
| | | | | Panel l | 3.1: Out | t-of-San | ple For | ecasting | g Ability | $\tau = 3$ | | | | |
| | Unre | stricted : | $\Delta IPI_{t,t+}$ | $\tau = \alpha + \mu$ | $\beta_I X_t + \beta_2$ | $_2VIX_t^2 + _2$ | $\varepsilon_{t,t+\tau}$ | Unrest | tricted : 2 | $\Delta IPI_{t,t+\tau}$ | $= \alpha + \beta_I$ | $X_t + \beta_2 l$ | $MOVE_t^2 +$ | $+ \varepsilon_{t,t+\tau}$ |
| | Re st. | ricted : Δ | $IPI_{t,t+\tau}$ | $= \alpha + \beta_l$ | $X_t + \varepsilon_{t,t+1}$ | -τ | | Re stri | $cted:\Delta I$ | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $\varepsilon_t + \varepsilon_{t,t+\tau}$ | - | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 0.995 | 0.903 | 1,006 | 0.895 | 0.907 | 0.966 | 0.934 | 0.994 | 0.922 | 0.991 | 0.947 | 0.943 | 0.997 | 0.963 |
| <i>p</i> -val (<i>t</i>) | 0.014 | 0.003 | 0.069 | 0.001 | 0.009 | 0.004 | 0.007 | 0.016 | 0.002 | 0.005 | 0.004 | 0.011 | 0.030 | 0.006 |
| p-val (F) | 0.000 | 0.000 | 0.687 | 0.000 | 0.000 | 0.000 | 0.000 | 0.002 | 0.000 | 0.003 | 0.000 | 0.000 | 0.015 | 0.000 |
| | | | | | | | | | | | | | | |

Table A.1 Out-of-Sample Industrial Production Growth Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| | Panel C: In-Sample Forecasting Ability: $\tau = 6$ | | | | | | | | | | | | | |
|----------------------------|--|-------------------|----------------------|-------------------------|-----------------------------|-------------------|--------------------------|---|---------------------|-----------------------|-------------------------|------------------------------|---------------------------|----------------------------|
| | Δl | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $T_t + \beta_2 V L$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | | $\Delta IPI_{t,t+}$ | $\tau = \alpha + \mu$ | $\beta_1 X_t + \beta_2$ | $_2MOVE_t^2$ | $+\varepsilon_{t,t+\tau}$ | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.002 (2.81) | 0.002 (2.74) | 0.006 (3.59) | 0.004 (3.09) | 0.007 (3.00) | 0.004 (4.58) | 0.003 (7.62) | 0.002 (2.76) | 0.003 (2.61) | 0.006 (4.09) | 0.004 (2.62) | 0.008 (3.10) | 0.004 (4.58) | 0.004 (4.74) |
| $\hat{\beta}_l$ | 0.362 (2.10) | 0.049 (1.85) | -0.147 (-1.77) | -0.050 (-0.92) | -0.007 (-1.79) | -0.131 (-1.13) | -0.209 (-2.48) | 0.371 (2.43) | 0.073 (2.69) | -0.156 (-2.66) | -0.011 (-0.19) | -0.008 (-2.13) | -0.024 (-2.11) | -0.206 (-2.87) |
| $\hat{\beta}_2$ | -0.020 (-2.38) | -0.036 (-2.73) | -0.017 (-1.34) | -0.036 (-3.02) | -0.034 (-3.16) | -0.024 (-2.11) | -0.028 (-3.35) | -0.121 (-1.43) | -0.262 (-2.36) | -0.134 (-1.46) | -0.232 (-2.01) | -0.227 (-2.38) | -0.131 (-1.13) | -0.174 (-2.07) |
| Adj R ² | 0.234 | 0.150 | 0.174 | 0.134 | 0.176 | 0.150 | 0.185 | 0.225 | 0.163 | 0.187 | 0.115 | 0.172 | 0.150 | 0.171 |
| | | | | Panel (| C.1: Out | -of-San | ple For | ecasting | , Ability | $\tau = 6$ | | | | |
| | Unre | stricted : | $\Delta IPI_{t,t+}$ | $\tau = \alpha + \beta$ | $\beta_I X_t + \beta_2$ | $VIX_t^2 + d$ | $\varepsilon_{t,t+\tau}$ | Unrestricted : $\Delta IPI_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | |
| | Re st | ricted : Δ | $IPI_{t,t+\tau}$ | $= \alpha + \beta_l$ | $X_t + \varepsilon_{t,t+1}$ | -τ | | Re stri | cted : ΔL | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $t + \varepsilon_{t,t+\tau}$ | | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 1.008 | 0.943 | 1,012 | 0.933 | 0.952 | 0.996 | 0.979 | 0.989 | 0.925 | 0.989 | 0.948 | 0.947 | 0.990 | 0.971 |
| <i>p</i> -val (<i>t</i>) | 0.092 | 0.001 | 0.088 | 0.000 | 0.010 | 0.023 | 0.019 | 0.022 | 0.003 | 0.008 | 0.014 | 0.005 | 0.016 | 0.041 |
| p-val (F) | 0.706 | 0.000 | 0.922 | 0.000 | 0.000 | 0.005 | 0.000 | 0.001 | 0.000 | 0.000 | 0.000 | 0.000 | 0.003 | 0.001 |
| | | | | Pane | el D: In- | Sample | Forecas | ting Ab | ility: $	au$ = | = 12 | | | | |
| | Δl | $PI_{t,t+\tau} =$ | $\alpha + \beta_I X$ | $T_t + \beta_2 V L$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | $\Delta IPI_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.002 (3.21) | 0.001 (1.56) | 0.004 (2.88) | 0.002 (1.41) | 0.007 (2.99) | 0.003 (4.22) | 0.003 (6.81) | 0.002 (3.03) | 0.002 (2.24) | 0.004 (3.29) | 0.002 (1.44) | 0.007 (2.89) | 0.003 (4.22) | 0.003 (4.77) |
| $\hat{\beta}_{I}$ | 0.095 (0.57) | 0.060 (2.39) | -0.103 (-1.32) | 0.031 (0.62) | -0.008 (-1.85) | -0.079 (-0.67) | -0.248 (-2.34) | 0.089 (0.55) | 0.074 (2.65) | -0.094 (-1.72) | 0.055 (1.01) | -0.008 (-2.09) | -0.010 (-0.94) | -0.245 (-3.03) |
| $\hat{\beta}_2$ | -0.014 (-2.39) | -0.017 (-2.47) | -0.004 (-0.48) | -0.017 (-2.63) | -0.015 (-2.36) | -0.010 (-0.94) | -0.007 (-1.09) | -0.101 (-1.18) | -0.151 (-1.79) | -0.060 (-0.75) | -0.135 (-1.55) | -0.115 (-1.59) | -0.079 (-0.67) | -0.048 (-0.79) |
| Adj R ² | 0.043 | 0.081 | 0.066 | 0.039 | 0.107 | 0.047 | 0.128 | 0.045 | 0.105 | 0.073 | 0.048 | 0.114 | 0.047 | 0.128 |
| | | | | Panel D | 0.1: Out- | -of-Sam | ple Fore | ecasting | Ability | $\tau = 12$ | | | | |
| | Unre | stricted : | $\Delta IPI_{t,t+}$ | $\tau = \alpha + \beta$ | $\beta_I X_t + \beta_2$ | $2VIX_t^2 + 3$ | $\varepsilon_{t,t+\tau}$ | Unrest | ricted : 2 | $MPI_{t,t+\tau}$ | $= \alpha + \beta_l$ | $X_t + \beta_2 N$ | $MOVE_t^2$ - | $+ \varepsilon_{t,t+\tau}$ |
| | Re st | ricted : Δ | $IPI_{t,t+\tau}$ | $= \alpha + \beta_l$ | $X_t + \varepsilon_{t,t+1}$ | -τ | | Re stri | cted : ΔL | $PI_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $t + \varepsilon_{t,t+\tau}$ | | |
| | Lag IPI | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag IPI | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 1.005 | 0.987 | 1,018 | 0.981 | 1.007 | 1.013 | 1.026 | 0.998 | 0.972 | 1.004 | 0.980 | 0.996 | 1.001 | 1.009 |
| <i>p</i> -val (<i>t</i>) | 0.090 | 0.014 | 0.399 | 0.005 | 0.059 | 0.095 | 0.260 | 0.027 | 0.010 | 0.151 | 0.011 | 0.056 | 0.040 | 0.070 |
| p-val (F) | 0.502 | 0.000 | 0.981 | 0.000 | 0.432 | 0.856 | 0.996 | 0.018 | 0.000 | 0.221 | 0.000 | 0.019 | 0.057 | 0.868 |
| | | | | | | | | | | | | | | |

Table A.1 (continuation). Out-of-Sample Industrial Production Growth Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| | | inuti (C) | Stundun | Pan | el A: In | -Sample | e Foreca | sting Al | oility: τ | = 1 | | | | |
|-------------------------------|-------------------|----------------------|-------------------------|--------------------------|-------------------------------|--------------------------|---------------------------|---|-------------------|------------------------------------|--------------------------|-----------------------------------|------------------------------|--|
| | EXC | MKET _{t,t+} | $\tau = \alpha + \beta$ | $\beta_l X_t + \beta_l$ | $_{2}VIX_{t}^{2} +$ | $\varepsilon_{t,t+\tau}$ | | Ελ | CMKET | $\dot{\sigma}_{t,t+\tau} = \alpha$ | $+\beta_l X_t$ | + β ₂ ΜΟ | $VE_t^2 + \varepsilon_{t,i}$ | t+τ |
| | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.004 (0.86) | 0.005 (0.80) | 0.013 (1.35) | -0.004 (-0.41) | 0.025 (1.43) | 0.014 (1.95) | 0.007 (1.52) | 0.013 (2.08) | 0.012 (1.79) | 0.012 (1.17) | 0.002 (0.17) | 0.033 (1.85) | 0.014 (1.95) | 0.014 (2.21) |
| $\hat{\beta}_{I}$ | 0.092 (1.52) | 0.054 (0.27) | -0.383 (-0.88) | 0.480 (1.32) | -0.034 (-1.28) | -1.413 (-1.75) | -0.992 (-1.11) | 0.048 (0.90) | 0.130 (0.61) | 0.142 (0.35) | 0.676 (1.81) | -0.032 (-1.38) | 0.145 (1.92) | -0.550 (-0.81) |
| $\hat{\beta}_2$ | 0.052 (0.46) | 0.012 (0.10) | 0.060 (0.54) | 0.009 (0.07) | 0.020 (0.19) | 0.145 (1.92) | 0.056 (0.65) | -0.700 (-0.98) | -0.837 (-1.11) | -0.879 (-1.22) | -0.964 (-1.28) | -0.770 (-1.14) | -1.413 (-1.75) | -0.606 (-0.97) |
| Adj R ² | 0.001 | -0.005 | -0.003 | 0.000 | 0.003 | 0.017 | 0.005 | 0.008 | 0.007 | 0.006 | 0.016 | 0.014 | 0.017 | 0.009 |
| | | | | Panel | A.1: Ou | t-of-San | nple For | ecasting | g Ability | $\tau: \tau = I$ | | | | |
| | Unres | tricted : E | EXCMKET | $T_{t,t+\tau} = \alpha$ | $+\beta_l X_t +$ | $\beta_2 VIX_t^2 +$ | $-\varepsilon_{t,t+\tau}$ | Unrestr | ricted : EX | <i>KCMKET</i> | $a_{t+\tau} = \alpha$ | $+ \beta_l X_t + \beta_l X_t$ | β ₂ MOVE | $e_t^2 + \varepsilon_{t,t+\tau}$ |
| | Re str | icted : EX | CMKET _t , | $t+\tau = \alpha + \tau$ | $\beta_l X_t + \varepsilon_t$ | , <i>t</i> +7 | | Re stric | eted : EXC | CMKET _{t,t} | $+\tau = \alpha + \beta$ | $\beta_l X_t + \varepsilon_{t,t}$ | <i>t</i> +τ | |
| | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 1.010 | 1.013 | 1,007 | 1.016 | 1.013 | 1.002 | 1.010 | 1.008 | 1.007 | 1.005 | 1.004 | 1.009 | 0.997 | 1.009 |
| p-val (t) | 0.540 | 0.622 | 0.260 | 0.663 | 0.547 | 0.277 | 0.553 | 0.460 | 0.308 | 0.259 | 0.192 | 0.522 | 0.064 | 0.599 |
| <i>p</i> -val (<i>F</i>) | 0.473 | 0.608 | 0.303 | 0.731 | 0.557 | 0.250 | 0.512 | 0.476 | 0.374 | 0.288 | 0.193 | 0.577 | 0.073 | 0.586 |
| | | | | Pan | el B: In | -Sample | e Foreca | sting Al | oility: $	au$ | = 3 | | | | |
| | EXC | MKET _{t,t+} | $\tau = \alpha + \beta$ | $\beta_l X_t + \beta_l$ | $_{2}VIX_{t}^{2} +$ | $\varepsilon_{t,t+\tau}$ | | $EXCMKET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | $t+\tau$ | |
| | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| \hat{lpha} | 0.001 (0.34) | 0.003 (0.50) | 0.012 (1.36) | -0.007 (-0.78) | 0.020 (1.31) | 0.010 (1.83) | 0.005 (1.33) | 0.010 (1.97) | 0.008 (1.44) | 0.010 (1.03) | -0.002 (-0.27) | 0.025 (1.58) | 0.010 (1.83) | 0.010 (2.04) |
| $\hat{\beta}_l$ | 0.143 (1.56) | 0.089 (0.47) | -0.430 (-0.97) | 0.536 (1.62) | -0.028 (-1.16) | -0.988 (-1.65) | -0.732 (-1.07) | 0.035 (0.42) | 0.133 (0.71) | 0.045 (0.11) | 0.663 (1.95) | -0.026 (-1.15) | 0.127 (1.96) | -0.402 (-0.79) |
| $\hat{\beta}_2$ | 0.088 (0.99) | 0.035 (0.36) | 0.090 (0.96) | 0.032 (0.32) | 0.043 (0.48) | 0.127 (1.96) | 0.069 (0.93) | -0.380 (-0.70) | -0.488 (-0.86) | -0.467 (-0.90) | -0.606 (-1.06) | -0.418 (-0.80) | -0.988 (-1.65) | -0.287 (-0.57) |
| Adj R ² | 0.011 | -0.001 | 0.006 | 0.015 | 0.014 | 0.027 | 0.014 | 0.005 | 0.008 | 0.004 | 0.031 | 0.018 | 0.027 | 0.007 |
| | | | | Panel | B.1: Out | t-of-San | nple For | ecasting | , Ability | $\tau = 3$ | | | | |
| | Unres | tricted : E | EXCMKET | $T_{t,t+\tau} = \alpha$ | $+\beta_l X_t +$ | $\beta_2 VIX_t^2 +$ | $-\varepsilon_{t,t+\tau}$ | Unrestr | ricted : EX | KCMKET _i | $a_{t+\tau} = \alpha$ | $+\beta_l X_t + \beta_l X_t$ | β ₂ MOVE | $\frac{2}{t} + \varepsilon_{t,t+\tau}$ |
| | Re str | icted : EX | CMKET _t , | $t+\tau = \alpha + \tau$ | $\beta_l X_t + \varepsilon_t$ | <i>t+τ</i> | | Re stric | ted : EXC | CMKET _{t,t} | $+\tau = \alpha + \beta$ | $\beta_I X_t + \varepsilon_t$ | <i>t</i> + <i>τ</i> | |
| | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 1.004 | 1.017 | 1,006 | 1.015 | 1.012 | 0.997 | 1.008 | 1.005 | 1.003 | 1.003 | 0.999 | 1.007 | 0.989 | 1.006 |
| <i>p</i> -val (<i>t</i>) | 0.066 | 0.291 | 0.066 | 0.158 | 0.168 | 0.064 | 0.097 | 0.113 | 0.057 | 0.068 | 0.033 | 0.106 | 0.006 | 0.117 |
| <i>p</i> -val (<i>F</i>) | 0.309 | 0.982 | 0.534 | 0.995 | 0.887 | 0.051 | 0.508 | 0.286 | 0.219 | 0.152 | 0.029 | 0.682 | 0.002 | 0.556 |

Table A.2. Out-of-Sample Excess Market Return Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| MOV | $^{\prime}\mathrm{E}^{2}$ agai | inst Alt | ernativ | e Stand | ard Pre | dictors | , May 1 | 988-Ju | ne 201' | 7. | TOwer | 01 12 | x anu | |
|-------------------------------|--|----------------------|-------------------------|--------------------------------|-------------------------------|--------------------------|---------------------------|---|-------------------|-------------------------------|--|-----------------------------------|------------------------------|--|
| | | | | Pan | el C: In | -Sample | e Foreca | sting Al | bility: τ | = 6 | | | | |
| | EXC | MKET _{t,t+} | $\tau = \alpha + \beta$ | $\beta_l X_t + \beta_l$ | $_{2}VIX_{t}^{2} +$ | $\varepsilon_{t,t+\tau}$ | | ΕΣ | KCMKET | $\dot{t}_{t,t+\tau} = \alpha$ | $+\beta_l X_t$ | + β ₂ ΜΟ | $VE_t^2 + \varepsilon_{t,i}$ | $t+\tau$ |
| | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | -0.001 (-0.14) | 0.000 (0.06) | 0.010 (1.35) | -0.010 (-1.48) | 0.018 (1.37) | 0.008 (2.45) | 0.003 (1.36) | 0.008 (2.25) | 0.005 (1.26) | 0.006 (0.85) | -0.005 (-0.75) | 0.022 (1.58) | 0.008 (2.45) | 0.008 (2.37) |
| $\hat{\beta}_{I}$ | 0.181 (1.45) | 0.165 (1.05) | -0.418 (-1.02) | 0.611 (2.13) | -0.027 (-1.20) | -0.862 (-1.79) | -0.583 (-1.08) | -0.006 (-0.04) | 0.192 (1.22) | 0.096 (0.27) | 0.699 (2.23) | -0.024 (-1.14) | 0.146 (2.83) | -0.257 (-0.66) |
| $\hat{\beta}_2$ | 0.120 (2.13) | 0.066 (1.25) | 0.120 (2.17) | 0.064 (1.19) | 0.074 (1.47) | 0.146 (2.83) | 0.095 (2.04) | -0.236 (-0.65) | -0.301 (-0.79) | -0.290 (-0.93) | -0.396 (-1.08) | -0.205 (-0.56) | -0.862 (-1.79) | -0.112 (-0.30) |
| Adj R ² | 0.034 | 0.024 | 0.029 | 0.056 | 0.041 | 0.054 | 0.034 | -0.001 | 0.013 | 0.000 | 0.052 | 0.021 | 0.054 | 0.001 |
| | | | | Panel | C.1: Out | t-of-San | ple For | ecasting | g Ability | $\tau: \tau = 6$ | | | | |
| | Unres | tricted : E | EXCMKET | $T_{t,t+\tau} = \alpha$ | $+ \beta_l X_t +$ | $\beta_2 VIX_t^2 +$ | $\varepsilon_{t,t+\tau}$ | Unrest | ricted : EX | KCMKET | $\dot{t}_{t,t+\tau} = \alpha - \alpha$ | $+\beta_l X_t + \beta_l X_t$ | $\beta_2 MOVE_1$ | $\frac{2}{t} + \varepsilon_{t,t+\tau}$ |
| | Re str | ,t+T | | Re stric | cted : EXC | CMKET _{t,t} | $+\tau = \alpha + \beta$ | $\beta_l X_t + \varepsilon_t$ | $t+\tau$ | | | | | |
| | Lag EXC TERM DEF DY HJ Move ² TEI MKT | | | | | | | | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 0.983 | 1.008 | 0.988 | 0.996 | 0.996 | 0.977 | 0.989 | 1.005 | 1.003 | 1.004 | 1.000 | 1.007 | 0.983 | 1.007 |
| <i>p</i> -val (<i>t</i>) | 0.004 | 0.117 | 0.017 | 0.019 | 0.036 | 0.005 | 0.008 | 0.107 | 0.046 | 0.196 | 0.029 | 0.117 | 0.001 | 0.183 |
| <i>p</i> -val (<i>F</i>) | 0.000 | 0.612 | 0.001 | 0.008 | 0.016 | 0.003 | 0.001 | 0.297 | 0.152 | 0.322 | 0.027 | 0.705 | 0.000 | 0.689 |
| | | | | Pane | el D: In- | Sample | Forecas | sting Ab | oility: $	au$ = | = 12 | | | | |
| | EXC | MKET _{t,t+} | $\tau = \alpha + \beta$ | $\beta_l X_t + \beta_l$ | $_{2}VIX_{t}^{2} +$ | $\varepsilon_{t,t+\tau}$ | | $EXCMKET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | $t+\tau$ | |
| | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EXC MKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.001 (0.51) | -0.002 (-0.56) | 0.006 (1.07) | -0.009 (1.71) | 0.018 (1.93) | 0.006 (2.48) | 0.004 (2.05) | 0.007 (1.77) | 0.002 (0.57) | 0.004 (0.66) | -0.006 (-1.06) | 0.020 (1.82) | 0.006 (2.48) | 0.006 (1.82) |
| $\hat{\beta}_{I}$ | 0.130 (0.89) | 0.274 (2.28) | -0.138 (-0.49) | 0.602 (2.55) | -0.027 (-1.59) | -0.490 (-1.23) | -0.695 (-1.51) | -0.020 (-0.13) | 0.293 (2.30) | 0.162 (0.62) | 0.665 (2.51) | -0.025 (-1.49) | 0.093 (2.11) | -0.470 (-1.18) |
| $\hat{\beta}_2$ | 0.074 (2.46) | 0.048 (1.70) | 0.066 (2.12) | 0.044 (1.75) | 0.055 (1.67) | 0.093 (2.11) | 0.081 (2.14) | -0.113 (-0.33) | -0.203 (-0.59) | -0.195 (-0.61) | -0.249 (-0.77) | -0.065 (-0.19) | -0.490 (-1.23) | 0.099 (0.32) |
| Adj R ² | 0.024 | 0.070 | 0.016 | 0.088 | 0.065 | 0.039 | 0.058 | -0.004 | 0.058 | 0.001 | 0.082 | 0.040 | 0.039 | 0.013 |
| | | | | Panel D | 0.1: Out | -of-Sam | ple Fore | ecasting | Ability | $\tau = 12$ | | | | |
| | Unres | tricted : E | EXCMKET | $T_{t,t+\tau} = \alpha$ | $+\beta_I X_t +$ | $\beta_2 VIX_t^2 +$ | $-\varepsilon_{t,t+\tau}$ | Unrest | ricted : EX | KCMKET | $\dot{a}_{t,t+\tau} = \alpha - \alpha$ | $+\beta_l X_t + \beta_l X_t$ | $\beta_2 MOVE_1$ | $e_t^2 + \varepsilon_{t,t+\tau}$ |
| | Re str | icted : EX | CMKET _t , | $t_{t+\tau} = \alpha + \alpha$ | $\beta_l X_t + \varepsilon_t$ | ,t+T | | Re stric | cted : EXC | CMKET _{t,t} | $+\tau = \alpha + \beta$ | $\beta_I X_t + \varepsilon_{t,t}$ | <i>t</i> +τ | |
| | Lag EMKT | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag EMKT | TERM | DEF | DY | HJ VOL | Vix ² | TED |

RMSE

p-val

(*t*) p-val

(F)

0.987

0.002

0.000

1.009

0.229

0.911

0.997

0.040

0.018

0.995

0.028

0.008

0.999

0.034

0.032

0.986

0.003

0.000

0.989

0.019

0.002

1.007

0.079

0.771

1.007

0.108

0.643

1.004

0.131

0.504

1.002

0.105

0.145

1.018

0.216

0.996

Table A.2 (continuation). Out-of-Sample Excess Market Return Forecasting Power of VIX² and

0.994

0.023

0.005

1.010

0.227

0.776

| MOV | E ² agai | inst Alt | ernative | e Stand | ard Pre | dictors | , May I | 988-Ju | ne 201 | /. | | | | |
|--|--|-------------------|----------------------|----------------------------|--|--------------------------|-------------------|--|-------------------|--|---------------------------|-----------------------------|---|--------------------------|
| | | | | Pan | el A: In | -Sample | e Foreca | sting Al | bility: $	au$ | = 1 | | | | |
| | $TRYRET_{t,t+\tau} = \alpha + \beta_I X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | $\alpha_{+\tau} = \alpha + \alpha_{+\tau}$ | $\beta_l X_t +$ | β ₂ MOVE | $\varepsilon_t^2 + \varepsilon_{t,t+1}$ | τ |
| | Lag TRY RET | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag TRY RET | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | -0.001 (-0.58) | -0.001 (-0.46) | 0.007 (1.52) | -0.004 (-0.79) | 0.002 (0.33) | 0.001 (0.35) | -0.001 (-0.38) | 0.001 (0.26) | 0.001 (0.32) | 0.002 (0.44) | -0.001 (-0.24) | 0.003 (0.46) | 0.001 (0.35) | 0.001 (0.42) |
| $\hat{\beta}_{I}$ | 0.242 (5.09) | -0.005 (-0.05) | -0.513 (-2.09) | 0.108 (0.52) | -0.006 (-0.60) | -0.398 (-1.47) | -0.234 (-1.01) | 0.256 (5.75) | -0.014 (-0.13) | -0.088 (-0.39) | 0.111 (0.55) | -0.004 (-0.40) | 0.113 (2.33) | -0.034 (-0.13) |
| $\hat{\beta}_2$ | 0.057 (1.45) | 0.076 (0.88) | 0.141 (3.27) | 0.075 (1.87) | 0.077 (1.92) | 0.113 (2.33) | 0.084 (1.89) | 0.071 (0.27) | 0.096 (0.29) | 0.146 (0.44) | 0.062 (0.18) | 0.094 (0.28) | -0.398 (-1.47) | 0.074 (0.22) |
| Adj R ² | 0.072 | 0.014 | 0.034 | 0.015 | 0.016 | 0.021 | 0.016 | 0.062 | -0.005 | -0.004 | -0.004 | -0.005 | 0.021 | -0.006 |
| | | | | Panel A | 4.1: Out | ecasting | g Ability | $\tau = I$ | | | | | | |
| | Unre | estricted : | TRYRET _{t,} | $t+\tau = \alpha + \tau$ | $\beta_l X_t + \beta$ | $V_2 VIX_t^2 + e^{2t}$ | $s_{t,t+\tau}$ | Unrest | ricted : Tl | $RYRET_{t,t+}$ | $a_{\tau} = \alpha + \mu$ | $\beta_l X_t + \beta_2$ | $MOVE_t^2 +$ | $\varepsilon_{t,t+\tau}$ |
| | Re st | ricted : Tl | $RYRET_{t,t+}$ | $\tau = \alpha + \beta$ | $\mathcal{E}_{l}X_{t} + \mathcal{E}_{t,t}$ | +τ | | Re stri | cted : TRY | $\mathcal{R}ET_{t,t+\tau}$ | $= \alpha + \beta_{l}$ | $X_t + \varepsilon_{t,t+1}$ | r | |
| | Lag TRY RET | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag TRY RET | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 1.006 | 1.005 | 0.986 | 1.011 | 1.005 | 0.993 | 1.000 | 1.014 | 1.015 | 1.009 | 1.015 | 1.017 | 1.004 | 1.014 |
| <i>p</i> -val (<i>t</i>) | 0.231 | 0.149 | 0.011 | 0.204 | 0.420 | 0.047 | 0.093 | 0.770 | 0.674 | 0.399 | 0.589 | 0.471 | 0.444 | 0.600 |
| p-val (F) | 0.398 | 0.327 | 0.004 | 0.671 | 0.453 | 0.030 | 0.095 | 0.858 | 0.860 | 0.593 | 0.864 | 0.578 | 0.513 | 0.827 |
| Panel B: In-Sample Forecasting Ability: $\tau = 3$ | | | | | | | | | | | | | | |
| | TRY | $RET_{t,t+\tau}$ | $= \alpha + \beta_I$ | $X_t + \beta_2 V$ | $VIX_t^2 + \varepsilon_t$ | $t,t+\tau$ | | $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | |
| | Lag TRY RET | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag TRY RET | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| â | 0.000 (0.25) | -0.001 (-0.38) | 0.009 (2.29) | -0.001 (-0.12) | 0.003 (0.50) | 0.000 (0.02) | 0.003 (1.36) | 0.000 (0.02) | -0.001 (-0.34) | 0.005 (1.30) | -0.000 (-0.08) | 0.002 (0.36) | 0.000 (0.02) | 0.001 (0.26) |
| $\hat{\beta}_{I}$ | -0.012 (-0.18) | 0.079 (0.79) | -0.473 (-2.58) | 0.049 (0.25) | -0.005 (-0.47) | 0.079 (0.35) | 0.606 (2.10) | 0.000 (0.00) | 0.066 (0.65) | -0.304 (-1.62) | 0.020 (0.10) | -0.004 (-0.41) | 0.021 (0.53) | 0.353 (1.65) |
| $\hat{\beta}_2$ | 0.029 (0.78) | 0.028 (0.80) | 0.089 (2.48) | 0.028 (0.79) | 0.030 (0.86) | 0.021 (0.53) | -0.064 (-1.71) | 0.170 (0.77) | 0.145 (0.64) | 0.362 (1.37) | 0.164 (0.74) | 0.173 (0.78) | 0.079 (0.35) | 0.015 (0.08) |
| Adj R ² | 0.001 | 0.005 | 0.039 | 0.001 | 0.002 | 0.001 | 0.016 | -0.000 | 0.002 | 0.020 | -0.001 | 0.000 | 0.001 | 0.010 |
| | | | | Panel I | B.1: Out | -of-San | ple For | ecasting | g Ability | : <i>τ</i> = 3 | | | | |
| | Unre | estricted : | TRYRET _{t,} | $t+\tau = \alpha + \alpha$ | $\beta_l X_t + \beta_l X_t$ | $V_2 VIX_t^2 + \epsilon$ | $S_{t,t+\tau}$ | Unrest | ricted : Th | RYRET _{t,t+} | $a_{\tau} = \alpha + \mu$ | $\beta_1 X_t + \beta_2$ | $MOVE_t^2 +$ | $\varepsilon_{t,t+\tau}$ |
| | Restricted : TRYRET _{t,t+τ} = $\alpha + \beta_I X_t + \varepsilon_{t,t+\tau}$ | | | | | | | | | $RET_{t,t+\tau}$ | $= \alpha + \beta_1$ | $X_t + \varepsilon_{t,t+1}$ | T | |
| | Lag TRY RET | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag TRY RET | TERM | DEF | DY | HJ VOL | Vix ² | TED |
| RMSE | 1.006 | 1.003 | 0.983 | 1.007 | 1.006 | 1.004 | 1.009 | 1.006 | 1.007 | 0.996 | 1.005 | 1.009 | 1.005 | 1.006 |
| <i>p</i> -val (<i>t</i>) | 0.085 | 0.120 | 0.011 | 0.179 | 0.060 | 0.100 | 0.253 | 0.244 | 0.333 | 0.022 | 0.199 | 0.344 | 0.331 | 0.440 |
| p-val (F) | 0.371 | 0.197 | 0.000 | 0.721 | 0.525 | 0.291 | 0.559 | 0.431 | 0.678 | 0.011 | 0.258 | 0.906 | 0.463 | 0.472 |
| | | | | | | | | | | | | | | |

Table A.3. Out-of-Sample Excess Treasury Bond Return Forecasting Power of VIX² and $MOVE^2$ against Alternative Standard Predictors, May 1988-June 2017.

VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017. Panel C: In-Sample Forecasting Ability: $\tau = 6$ $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ Lag TRY Lag TRY HJ HJ TERM DEF TERM DEF DY Vix² DY Move² TED TED VOL VOL RET RET 0.002 0.000 0.005 0.002 0.002 0.002 0.000 0.005 0.002 0.007 0.002 0.006 0.001 0.002 â (1.45) (0.97) (0.34)(2.47)(1.03)(0.95)(0.07)(2.16)(0.93)(0.95)(1.31)(0.12)(0.46)(1.32)-0 159 0.099 -0 308 0.023 -0.006 0.068 0.243 -0 161 0.103 -0.270 0.022 -0.006 -0.016 0.231 $\hat{\beta}_{I}$ (1.54) (0.40)(-1.92)(-1.52) (1.15)(-2.10)(0.14)(-0.65)(-1.55)(1.18)(0.13)(-0.68)(-0.62)(1.49)-0.039 0.174 0.000 -0.009 0.030 -0.009 -0.008 -0.016 -0.023 0.027 -0.005 0.006 0.068 -0.118 $\hat{\beta}_2$ (0.01)(-0.45) (1.28)(-0.46) (-0.39)(-0.62) (-1.12) (0.20)(-0.27) (1.07)(-0.04) (0.05)(0.40)(-0.82) $Adj R^2$ 0.019 0.009 0.027 -0.004 0.000 -0.004 0.009 0.020 0.008 0.027 -0.006 -0.001 -0.004 0.005 Panel C.1: Out-of-Sample Forecasting Ability: $\tau = 6$ Unrestricted : $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ Unrestricted : $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ *Restricted* : *TRYRET*_{$t,t+\tau$} = $\alpha + \beta_I X_t + \varepsilon_{t,t+\tau}$ Restricted : TRYRET_{t,t+ τ} = $\alpha + \beta_1 X_t + \varepsilon_{t,t+\tau}$ Lag Lag HJ HJ TRY TERM DEF DY Move² TED TRY TERM DEF DY Vix² TED VOL VOL RET RET 1.010 1.007 RMSE 1.009 1.007 1.000 1.005 1.002 1.010 1.011 1.002 1.007 1.009 1.007 1.005 p-val 0.359 0.320 0.271 0.479 0.123 0.058 0.121 0.096 0.453 0.292 0.106 0.247 0.217 0.147 (*t*) p-val 0.876 0.387 0.142 0.520 0.352 0.518 0.061 0.740 0.733 0.878 0.152 0.384 0.846 0.612 (F)Panel D: In-Sample Forecasting Ability: $\tau = 12$ $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ Lag TRY Lag TRY HJ HI TERM DEF TED TERM DEF Vix² TED DY Move² DY VOL VOL RET RET 0.002 0.000 0.006 0.002 0.0040.001 0.002 0.001 0.000 0.005 0.001 0.006 0.001 0.010 $\hat{\alpha}$ (1.93)(0.27)(3.07)(0.64)(0.98)(0.84)(1.70)(1.01)(0.00)(2.65)(0.44)(1.59)(0.84)(2.16)-0.414 0.076 -0.263 0.004 -0.003 0.114 0.084 -0.416 0.074-0.242 -0.007 0.208 -0.016 -0.024 βı (-4.75) (1.25)(-2.44) (0.03)(-0.50) (0.97)(0.80)(-5.04) (1.18)(-2.78) (-0.05) (1.32)(-0.82) (-0.13) 0.007 -0.006 0.028 -0.006 -0.005 -0.016 -0.011 0.102 0.016 0.204 0.046 -0.054 0.114 -0.215 $\hat{\beta}_2$ (0.50)(-0.36) (1.30)(-0.36) (-0.32) (-0.82) (-0.71) (0.15)(2.05) (0.43) (-0.21) (-0.85) (1.06)(0.97) $Adj R^2$ 0.160 0.015 0.049 -0.005 -0.002 0.001 -0.001 0.167 0.014 0.058 -0.004 0.041 0.001 0.002 Panel D.1: Out-of-Sample Forecasting Ability: $\tau = 12$ Unrestricted : $TRYRET_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ Unrestricted : $TRYRET_{t,t+\tau} = \alpha + \beta_I X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ Restricted : $TRYRET_{t,t+\tau} = \alpha + \beta_I X_t + \varepsilon_{t,t+\tau}$ Restricted : $TRYRET_{t,t+\tau} = \alpha + \beta_I X_t + \varepsilon_{t,t+\tau}$ Lag TRY Lag TRY HJ HJ TERM TERM DEF DY Move² TED DEF DY Vix² TED VOL VOL RET RET RMSE 1.020 1.069 1.027 1.028 1.050 1.034 1.043 1.004 1.0180.995 1.007 1.006 0.995 1.004p-val 0.172 0.369 0.228 0.140 0.430 0.2480.317 0.0400.902 0.025 0.194 0.121 0.018 0.076 (*t*) p-val 0.970 1.000 0.979 01.000 1.000 0.999 1.000 0.314 0.963 0.009 0.832 0.638 0.006 0.222 (F)

Table A.3 (continuation). Out-of-Sample Excess Treasury Bond Return Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| Panel A: In-Sample Forecasting Ability: $\tau = 1$ | | | | | | | | | | | | | | | | | |
|--|---|-------------------|------------------------|------------------------------|-----------------------------|---------------------------|-------------------|---|-------------------|--|------------------------|------------------------------|-------------------------|-------------------|--|--|--|
| | $HML_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | $HML_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| â | 0.006 (3.01) | 0.007 (1.40) | 0.001 (0.20) | 0.013 (1.61) | 0.022 (2.76) | 0.008 (2.19) | 0.009 (3.84) | 0.007 (1.84) | 0.007 (1.15) | 0.008 (1.25) | 0.012 (1.32) | 0.024 (2.65) | 0.008 (2.19) | 0.009 (2.21) | | | |
| $\hat{\beta}_{l}$ | 0.156 (2.58) | 0.015 (0.07) | 0.355 (1.16) | -0.284 (-0.82) | -0.026 (-1.96) | -0.118 (-2.20) | -0.522 (-1.24) | 0.167 (2.73) | 0.071 (0.32) | -0.011 (-0.04) | -0.201 (-0.58) | -0.028 (-2.03) | -0.079 (-0.19) | -0.633 (-1.47) | | | |
| $\hat{\beta}_2$ | -0.112 (-2.91) | -0.126 (-3.19) | -0.171 (-3.85) | -0.124 (-3.07) | -0.119 (-3.00) | -0.079 (-0.19) | -0.109 (-2.53) | -0.535 (-1.53) | -0.615 (-1.62) | -0.582 (-1.66) | -0.537 (-1.43) | -0.572 (-1.69) | -0.118 (-2.20) | -0.409 (-1.18) | | | |
| Adj R ² | 0.047 | 0.022 | 0.027 | 0.026 | 0.033 | 0.023 | 0.032 | 0.036 | 0.009 | 0.008 | 0.010 | 0.020 | 0.023 | 0.019 | | | |
| | | | | Panel A | 4.1: Out | ecasting | g Ability | $: \tau = I$ | | | | | | | | | |
| | Uni | restricted | : HML _{t,t+} | $a_{\tau} = \alpha + \beta$ | $\beta_1 X_t + \beta_2$ | $VIX_t^2 + \varepsilon_t$ | $t+\tau$ | Unre | estricted : | $HML_{t,t+\tau}$ | $= \alpha + \beta_1$ | $X_t + \beta_2 M$ | $OVE_t^2 + \varepsilon$ | $t.t+\tau$ | | | |
| | Re | stricted : | $HML_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \varepsilon_{t,t+1}$ | τ | | Re st | tricted : H | $ML_{t,t+\tau} =$ | $\alpha + \beta_l X_l$ | $t + \varepsilon_{t,t+\tau}$ | | * | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| RMSE | 0.996 | 0.991 | 0.989 | 0.992 | 0.993 | 1.005 | 0.998 | 1.000 | 0.998 | 0.997 | 1.000 | 1.001 | 1.005 | 1.002 | | | |
| <i>p</i> -val (<i>t</i>) | 0.062 | 0.040 | 0.049 | 0.044 | 0.461 | 0.846 | 0.127 | 0.100 | 0.083 | 0.087 | 0.110 | 0.471 | 0.851 | 0.278 | | | |
| <i>p</i> -val (<i>F</i>) | 0.033 | 0.008 | 0.020 | 0.013 | 0.365 | 0.722 | 0.101 | 0.096 | 0.064 | 0.082 | 0.106 | 0.476 | 0.728 | 0.304 | | | |
| | Panel B: In-Sample Forecasting Ability: $\tau = 3$ | | | | | | | | | | | | | | | | |
| | HI | $ML_{t,t+\tau} =$ | $= \alpha + \beta_l X$ | $X_t + \beta_2 V I$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | $HML_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| â | 0.006 (2.73) | 0.007 (1.41) | -0.002 (-0.48) | 0.012 (1.49) | 0.021 (2.96) | 0.006 (1.70) | 0.008 (3.58) | 0.006 (1.39) | 0.005 (0.95) | 0.005 (0.81) | 0.010 (1.14) | 0.024 (2.68) | 0.006 (1.70) | 0.006 (1.61) | | | |
| $\hat{\beta}_I$ | 0.091 (0.77) | 0.003 (0.01) | 0.519 (2.25) | -0.248 (-0.75) | -0.025 (-2.20) | 0.090 (0.26) | -0.494 (-1.95) | 0.118 (1.12) | 0.045 (0.23) | 0.083 (0.43) | -0.187 (-0.57) | -0.028 (-2.29) | -0.124 (-2.78) | -0.658 (-2.16) | | | |
| $\hat{\beta}_2$ | -0.110 (-2.35) | -0.116 (-2.68) | -0.182 (-4.20) | -0.115 (-2.66) | -0.109 (-2.61) | -0.124 (-2.78) | -0.098 (-2.52) | -0.435 (-1.08) | -0.464 (-1.15) | -0.500 (-1.29) | -0.399 (-0.99) | -0.425 (-1.18) | 0.090 (0.26) | -0.232 (-0.68) | | | |
| Adj R ² | 0.060 | 0.052 | 0.076 | 0.059 | 0.076 | 0.052 | 0.071 | 0.027 | 0.014 | 0.014 | 0.017 | 0.043 | 0.052 | 0.038 | | | |
| Panel B.1: Out-of-Sample Forecasting Ability: $\tau = 3$ | | | | | | | | | | | | | | | | | |
| | Unrestricted : $HML_{t,t+\tau} = \alpha + \beta_I X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | Unrestricted : $HML_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | |
| | Restricted : $HML_{t,t+\tau} = \alpha + \beta_l X_t + \varepsilon_{t,t+\tau}$ | | | | | | | | | <i>Restricted</i> : $HML_{t,t+\tau} = \alpha + \beta_I X_t + \varepsilon_{t,t+\tau}$ | | | | | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| RMSE | 0.988 | 0.976 | 0.964 | 0.973 | 0.981 | 0.990 | 0.992 | 0.999 | 0.997 | 0.993 | 1.000 | 1.003 | 1.004 | 1.003 | | | |
| <i>p</i> -val (<i>t</i>) | 0.020 | 0.013 | 0.009 | 0.002 | 0.021 | 0.024 | 0.018 | 0.045 | 0.033 | 0.010 | 0.010 | 0.054 | 0.197 | 0.112 | | | |
| p-val (F) | 0.000 | 0.000 | 0.000 | 0.000 | 0.001 | 0.001 | 0.004 | 0.036 | 0.015 | 0.000 | 0.010 | 0.115 | 0.445 | 0.169 | | | |
| | | | | | | | | | | | | | | | | | |

Table A.4 Out-of-Sample *HML* Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| | Panel C: In-Sample Forecasting Ability: $\tau = 6$ | | | | | | | | | | | | | | |
|-------------------------------|---|-------------------|------------------------|------------------------------|-----------------------------|---|-------------------|---|----------------------|-------------------|------------------------|------------------------------|----------------------|------------------------|--|
| | HN | $ML_{t,t+\tau} =$ | $= \alpha + \beta_I X$ | $t_t + \beta_2 V L$ | $X_t^2 + \varepsilon_{t,t}$ | $HML_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | |
| â | 0.004 (1.98) | 0.004 (0.93) | -0.005 (-1.19) | 0.008 (1.01) | 0.018 (2.71) | 0.004 (1.29) | 0.005 (2.45) | 0.003 (1.09) | 0.003 (0.72) | -0.000 (-0.02) | 0.007 (0.86) | 0.018 (2.59) | 0.004 (1.29) | 0.004 (1.25) | |
| $\hat{\beta}_l$ | 0.062 (0.51) | 0.005 (0.03) | 0.492 (2.61) | -0.177 (-0.56) | -0.025 (-2.30) | 0.038 (0.13) | -0.393 (-1.63) | 0.075 (0.66) | 0.024 (0.15) | 0.228 (1.44) | -0.152 (-0.48) | -0.026 (-2.32) | -0.057 (-1.35) | -0.479 (-1.91) | |
| $\hat{\beta}_2$ | -0.050 (-1.43) | -0.053 (-1.58) | -0.116 (-3.48) | -0.052 (-1.49) | -0.046 (-1.32) | -0.057 (-1.35) | -0.037 (-1.05) | -0.192 (-0.70) | -0.216 (-0.82) | -0.354 (-1.25) | -0.171 (-0.63) | -0.182 (-0.79) | 0.038 (0.13) | -0.042 (-0.18) | |
| Adj R ² | 0.019 | 0.016 | 0.055 | 0.022 | 0.056 | 0.016 | 0.032 | 0.007 | 0.001 | 0.013 | 0.006 | 0.046 | 0.016 | 0.023 | |
| | | | | Panel C | C.1: Out | ecasting | Ability | $: \tau = 6$ | | | | | | | |
| | Un | restricted | : HML _{t,t+} | $a_{\tau} = \alpha + \beta$ | $\beta_1 X_t + \beta_2 V$ | Unre | stricted : | $HML_{t,t+\tau}$ | $= \alpha + \beta_1$ | $X_t + \beta_2 M$ | $OVE_t^2 + \epsilon$ | ξt.t+τ | | | |
| | Re | stricted : | $HML_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \varepsilon_{t,t+1}$ | - | | Re st. | ricted : H | $ML_{t,t+\tau} =$ | $\alpha + \beta_l X_l$ | $t + \varepsilon_{t,t+\tau}$ | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | |
| RMSE | 1.011 | 0.996 | 0.980 | 0.996 | 1.007 | 1.012 | 1.015 | 1.006 | 1.006 | 0.996 | 1.006 | 1.004 | 1.008 | 1.006 | |
| <i>p</i> -val (<i>t</i>) | 0.129 | 0.037 | 0.001 | 0.008 | 0.048 | 0.117 | 0.113 | 0.170 | 0.064 | 0.021 | 0.133 | 0.053 | 0.624 | 0.231 | |
| p-val (F) | 0.929 | 0.014 | 0.000 | 0.000 | 0.599 | 0.758 | 0.973 | 0.522 | 0.397 | 0.008 | 0.770 | 0.207 | 0.704 | 0.298 | |
| | Panel D: In-Sample Forecasting Ability: $\tau = 12$ | | | | | | | | | | | | | | |
| | HN | $AL_{t,t+\tau} =$ | $\alpha + \beta_1 X$ | $f_t + \beta_2 V I$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | $HML_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | |
| â | 0.003 (1.86) | 0.002 (0.48) | -0.003 (-0.75) | 0.006 (0.91) | 0.012 (2.45) | 0.002 (1.12) | 0.003 (2.05) | 0.002 (1.03) | 0.001 (0.31) | 0.000 (0.00) | 0.005 (0.76) | 0.012 (2.42) | 0.002 (1.12) | 0.002 (0.86) | |
| $\hat{\beta}_l$ | -0.029 (-0.17) | 0.074 (0.59) | 0.315 (1.99) | -0.135 (-0.49) | -0.016 (-1.94) | 0.109 (0.54) | -0.215 (-1.22) | -0.022 (-0.13) | 0.081 (0.63) | 0.136 (1.06) | -0.138 (-0.49) | -0.017 (-1.96) | -0.036 (-1.17) | -0.312 (-1.51) | |
| $\hat{\beta}_2$ | -0.027 (-1.28) | -0.026 (-1.27) | -0.067 (-2.53) | -0.025 (-1.07) | -0.022 (-0.93) | -0.036 (-1.17) | -0.016 (-0.67) | -0.050 (-0.35) | -0.079 (-0.57) | -0.137 (-0.83) | -0.013 (-0.09) | -0.031 (-0.25) | 0.109 (0.54) | 0.077 (0.50) | |
| Adj R ² | 0.004 | 0.011 | 0.033 | 0.010 | 0.036 | 0.006 | 0.010 | -0.005 | 0.003 | 0.002 | 0.001 | 0.030 | 0.006 | 0.008 | |
| | Panel D.1: Out-of-Sample Forecasting Ability: $\tau = 12$ | | | | | | | | | | | | | | |
| | Un | restricted | : HML _{t,t+} | $\tau = \alpha + \beta$ | $\beta_1 X_t + \beta_2 V_t$ | $\sqrt{IX_t^2} + \varepsilon_{t,t}$ | $t+\tau$ | Unre | stricted : | $HML_{t,t+\tau}$ | $= \alpha + \beta_1$ | $X_t + \beta_2 M$ | $OVE_t^2 + \epsilon$ | $\tilde{s}_{t,t+\tau}$ | |
| | Re | stricted : | $HML_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \varepsilon_{t,t+1}$ | - | | Re st. | ricted : H | $ML_{t,t+\tau} =$ | $\alpha + \beta_l X_l$ | $t + \varepsilon_{t,t+\tau}$ | | | |
| | Lag HML | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag HML | TERM | DEF | DY | HJ VOL | Vix ² | TED | |
| RMSE | 1.013 | 0.999 | 0.999 | 1.006 | 1.020 | 1.013 | 1.023 | 1.010 | 1.003 | 1.005 | 1.006 | 1.019 | 1.003 | 1.007 | |
| <i>p</i> -val (<i>t</i>) | 0.100 | 0.104 | 0.041 | 0.030 | 0.114 | 0.095 | 0.102 | 0.464 | 0.025 | 0.120 | 0.391 | 0.505 | 0.123 | 0.410 | |
| p-val (F) | 0.934 | 0.090 | 0.025 | 0.558 | 0.964 | 0.963 | 0.985 | 0.866 | 0.100 | 0.605 | 0.570 | 1.000 | 0.142 | 0.771 | |

Table A.4 (continuation). Out-of-Sample *HML* Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| Panel A: In-Sample Forecasting Ability: $\tau = 1$ | | | | | | | | | | | | | | | | |
|--|---|-------------------|----------------------|------------------------------|-----------------------------|---------------------------------|-------------------|---|---|-------------------|------------------------------|---------------------------|---------------------------|------------------------|--|--|
| $BAB_{t,t+\tau} = \alpha + \beta_I X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | $BAB_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | |
| â | 0.017 (5.97) | 0.012 (2.59) | 0.003 (0.38) | 0.024 (2.31) | 0.051 (4.55) | 0.016 (3.88) | 0.020 (5.63) | 0.014 (3.72) | 0.009 (1.79) | 0.017 (2.65) | 0.019 (1.86) | 0.052 (4.79) | 0.016 (3.88) | 0.016 (4.61) | | |
| $\hat{\beta}_l$ | 0.098 (1.24) | 0.360 (1.75) | 0.877 (1.75) | -0.251 (-0.60) | -0.058 (-3.29) | 0.430 (0.84) | -0.802 (-1.54) | 0.120 (1.37) | 0.453 (2.05) | -0.084 (-0.31) | -0.137 (-0.31) | -0.064 (-3.64) | -0.300 (-4.84) | -1.211 (-2.42) | | |
| $\hat{\beta}_2$ | -0.245 (-4.56) | -0.259 (-5.09) | -0.371 (-4.70) | -0.258 (-4.24) | -0.244 (-3.50) | -0.300 (-4.84) | -0.228 (-3.52) | -0.735 (-2.31) | -1.031 (-3.15) | -0.811 (-2.60) | -0.828 (-2.30) | -0.825 (-2.33) | 0.430 (0.84) | -0.484 (-1.30) | | |
| Adj R ² | 0.083 | 0.087 | 0.093 | 0.075 | 0.108 | 0.076 | 0.083 | 0.028 | 0.034 | 0.014 | 0.014 | 0.056 | 0.076 | 0.035 | | |
| | | | | Panel A | A.1: Out | ecasting | g Ability | : <i>τ</i> = 1 | | | | | | | | |
| | Un | restricted | $: BAB_{t,t+}$ | $\tau = \alpha + \beta$ | $\beta_1 X_t + \beta_2 V_t$ | $\sqrt{IX_t^2} + \varepsilon_t$ | $t+\tau$ | Unr | estricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \beta_2 M$ | $OVE_t^2 + \varepsilon$ | <i>t</i> , <i>t</i> +τ | | |
| | Re | stricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \varepsilon_{t,t+1}$ | | | Re s | tricted : B | $AB_{t,t+\tau} =$ | $\alpha + \beta_l X_t$ | $+\varepsilon_{t,t+\tau}$ | | , | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | |
| RMSE | 0.982 | 0.977 | 0.973 | 0.971 | 0.991 | 0.989 | 1.005 | 1.001 | 0.993 | 0.999 | 0.999 | 1.004 | 1.003 | 1.006 | | |
| <i>p</i> -val (<i>t</i>) | 0.005 | 0.003 | 0.016 | 0.002 | 0.588 | 0.160 | 0.178 | 0.138 | 0.059 | 0.150 | 0.088 | 0.602 | 0.911 | 0.496 | | |
| <i>p</i> -val (<i>F</i>) | 0.000 | 0.000 | 0.001 | 0.000 | 0.478 | 0.053 | 0.332 | 0.150 | 0.024 | 0.147 | 0.075 | 0.647 | 0.856 | 0.697 | | |
| | Panel B: In-Sample Forecasting Ability: $\tau = 3$ | | | | | | | | | | | | | | | |
| | B | $AB_{t,t+\tau} =$ | $\alpha + \beta_1 X$ | $t_t + \beta_2 VL$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | $BAB_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | |
| \hat{lpha} | 0.012 (3.32) | 0.007 (1.50) | 0.002 (0.73) | 0.016 (1.64) | 0.048 (4.52) | 0.013 (4.14) | 0.015 (4.30) | 0.009 (2.66) | 0.006 (1.31) | 0.014 (2.75) | 0.013 (1.41) | 0.049 (4.88) | 0.013 (4.14) | 0.013 (4.67) | | |
| $\hat{\beta}_l$ | 0.209 (2.05) | 0.411 (2.19) | 0.540 (1.34) | -0.091 (-0.23) | -0.059 (-3.43) | 0.185 (0.41) | -0.585 (-1.58) | 0.245 (2.30) | 0.485 (2.41) | -0.059 (-0.25) | 0.006 (0.02) | -0.063 (-3.59) | -0.189 (-2.32) | -0.828 (-2.19) | | |
| $\hat{\beta}_2$ | -0.139 (-2.11) | -0.171 (-3.13) | -0.240 (-2.76) | -0.171 (-2.68) | -0.155 (-2.07) | -0.189 (-2.32) | -0.148 (-2.12) | -0.353 (-1.32) | -0.810 (-3.30) | -0.592 (-2.20) | -0.631 (-2.20) | -0.579 (-2.07) | 0.185 (0.41) | -0.366 (-1.29) | | |
| Adj R ² | 0.118 | 0.119 | 0.094 | 0.077 | 0.164 | 0.078 | 0.089 | 0.074 | 0.076 | 0.019 | 0.018 | 0.118 | 0.078 | 0.042 | | |
| Panel B.1: Out-of-Sample Forecasting Ability: $\tau = 3$ | | | | | | | | | | | | | | | | |
| | Un | restricted | $: BAB_{t,t+}$ | $a_{\tau} = \alpha + \beta$ | $\beta_1 X_t + \beta_2 V_t$ | $/IX_t^2 + \varepsilon_{t,t}$ | t+T | Unr | estricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \beta_2 M$ | $OVE_t^2 + \varepsilon_t$ | <i>t,t+τ</i> | | |
| | Restricted : $BAB_{t,t+\tau} = \alpha + \beta_1 X_t + \varepsilon_{t,t+\tau}$ | | | | | | | | | $AB_{t,t+\tau} =$ | $\alpha + \beta_l X_l$ | $+\varepsilon_{t,t+\tau}$ | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | |
| RMSE | 1.018 | 0.992 | 1.003 | 0.987 | 1.038 | 1.021 | 1.046 | 1.007 | 0.987 | 1.003 | 0.998 | 1.008 | 1.005 | 1.009 | | |
| <i>p</i> -val (<i>t</i>) | 0.106 | 0.022 | 0.061 | 0.019 | 0.082 | 0.144 | 0.197 | 0.352 | 0.004 | 0.085 | 0.013 | 0.122 | 0.113 | 0.293 | | |
| p-val (F) | 0.998 | 0.001 | 0.203 | 0.000 | 0.999 | 0.991 | 1.000 | 0.611 | 0.000 | 0.162 | 0.011 | 0.485 | 0.261 | 0.939 | | |
| | | | | | | | | | | | | | | | | |

Table A.5 Out-of-Sample *BAB* Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

| Panel C: In-Sample Forecasting Ability: $\tau = 6$ | | | | | | | | | | | | | | | | | |
|--|-------------------|-------------------|----------------------|------------------------------|-----------------------------|-------------------------------------|-------------------|---|---|-------------------|------------------------------|---------------------------|---------------------------|------------------------|--|--|--|
| $BAB_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 VIX_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | $BAB_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| \hat{lpha} | 0.009 (3.10) | 0.005 (1.29) | 0.005 (0.80) | 0.011 (1.24) | 0.048 (5.14) | 0.011 (3.89) | 0.013 (4.86) | 0.006 (1.89) | 0.004 (0.98) | 0.011 (2.33) | 0.008 (0.95) | 0.048 (5.31) | 0.011 (3.89) | 0.011 (4.05) | | | |
| $\hat{\beta}_l$ | 0.264 (2.52) | 0.372 (2.06) | 0.406 (1.15) | 0.068 (0.18) | -0.063 (-4.03) | 0.265 (0.59) | -0.726 (-2.19) | 0.307 (2.90) | 0.419 (2.21) | -0.056 (-0.28) | 0.123 (0.30) | -0.066 (-4.08) | -0.143 (-2.36) | -0.962 (-2.81) | | | |
| $\hat{\beta}_2$ | -0.082 (-1.83) | -0.119 (-3.53) | -0.171 (-2.77) | -0.119 (-3.03) | -0.101 (-1.89) | -0.143 (-2.36) | -0.088 (-1.80) | -0.076 (-0.30) | -0.514 (-2.11) | -0.318 (-1.20) | -0.384 (-1.32) | -0.291 (-1.15) | 0.265 (0.59) | -0.037 (-0.14) | | | |
| Adj R ² | 0.121 | 0.111 | 0.072 | 0.057 | 0.209 | 0.060 | 0.085 | 0.094 | 0.073 | 0.006 | 0.008 | 0.173 | 0.060 | 0.055 | | | |
| | | | | Panel (| C.1: Out | ecasting | g Ability | $: \tau = 6$ | | | | | | | | | |
| | Un | restricted | : $BAB_{t,t+}$ | $\tau = \alpha + \beta$ | $\beta_1 X_t + \beta_2 V_t$ | $\sqrt{IX_t^2} + \varepsilon_{t,t}$ | $t+\tau$ | Unr | estricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \beta_2 M$ | $OVE_t^2 + \varepsilon_t$ | <i>t</i> , <i>t</i> +τ | | | |
| | Re | stricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \varepsilon_{t,t+1}$ | - | | Re s | tricted : B | $AB_{t,t+\tau} =$ | $\alpha + \beta_l X_t$ | $+\varepsilon_{t,t+\tau}$ | | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| RMSE | 1.014 | 0.980 | 0.993 | 0.983 | 1.027 | 1.010 | 1.037 | 1.007 | 0.994 | 1.002 | 1.000 | 1.009 | 1.004 | 1.007 | | | |
| <i>p</i> -val (<i>t</i>) | 0.125 | 0.024 | 0.039 | 0.006 | 0.047 | 0.032 | 0.096 | 0.266 | 0.003 | 0.108 | 0.035 | 0.085 | 0.107 | 0.361 | | | |
| <i>p</i> -val (<i>F</i>) | 0.998 | 0.000 | 0.004 | 0.000 | 0.997 | 0.758 | 0.998 | 0.547 | 0.000 | 0.080 | 0.035 | 0.659 | 0.266 | 0.619 | | | |
| Panel D: In-Sample Forecasting Ability: $\tau = 12$ | | | | | | | | | | | | | | | | | |
| | Ba | $AB_{t,t+\tau} =$ | $\alpha + \beta_l X$ | $t_t + \beta_2 VL$ | $X_t^2 + \varepsilon_{t,t}$ | +τ | | $BAB_{t,t+\tau} = \alpha + \beta_1 X_t + \beta_2 MOVE_t^2 + \varepsilon_{t,t+\tau}$ | | | | | | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| â | 0.009 (2.83) | 0.003 (0.69) | 0.005 (0.85) | 0.007 (0.89) | 0.044 (5.47) | 0.009 (3.57) | 0.012 (4.51) | 0.006 (1.59) | 0.002 (0.56) | 0.010 (2.16) | 0.005 (0.63) | 0.044 (5.55) | 0.009 (3.57) | 0.009 (3.40) | | | |
| $\hat{\beta}_l$ | 0.157 (1.02) | 0.436 (2.82) | 0.370 (1.42) | 0.190 (0.56) | -0.059 (-4.28) | 0.263 (0.69) | -0.957 (-2.53) | 0.208 (1.32) | 0.473 (2.89) | -0.024 (-0.13) | 0.230 (0.62) | -0.061 (-4.31) | -0.114 (-2.20) | -1.214 (-3.48) | | | |
| $\hat{\beta}_2$ | -0.071 (-1.75) | -0.090 (-3.38) | -0.138 (-2.83) | -0.091 (-2.85) | -0.074 (-1.58) | -0.114 (-2.20) | -0.049 (-1.12) | -0.054 (-0.21) | -0.416 (-2.06) | -0.215 (-0.85) | -0.287 (-1.21) | -0.175 (-0.81) | 0.263 (0.69) | 0.160 (0.72) | | | |
| Adj R ² | 0.070 | 0.162 | 0.067 | 0.054 | 0.248 | 0.054 | 0.112 | 0.041 | 0.131 | 0.002 | 0.010 | 0.216 | 0.054 | 0.102 | | | |
| Panel D.1: Out-of-Sample Forecasting Ability: $\tau = 12$ | | | | | | | | | | | | | | | | | |
| | Un | restricted | $: BAB_{t,t+}$ | $\tau = \alpha + \beta$ | $\beta_1 X_t + \beta_2 V_t$ | $\sqrt{IX_t^2} + \varepsilon_{t,t}$ | $t+\tau$ | Unr | estricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_1 \lambda$ | $X_t + \beta_2 M$ | $OVE_t^2 + \varepsilon_t$ | <i>t,t+τ</i> | | | |
| | Re | stricted : | $BAB_{t,t+\tau}$ | $= \alpha + \beta_l \lambda$ | $X_t + \varepsilon_{t,t+2}$ | - | | Re s | tricted : B | $AB_{t,t+\tau} =$ | $\alpha + \beta_l X_t$ | $+\varepsilon_{t,t+\tau}$ | | | | | |
| | Lag BAB | TERM | DEF | DY | HJ VOL | Move ² | TED | Lag BAB | TERM | DEF | DY | HJ VOL | Vix ² | TED | | | |
| RMSE | 1.009 | 0.973 | 0.977 | 0.991 | 1.016 | 0.992 | 1.038 | 1.006 | 0.995 | 1.004 | 1.000 | 1.011 | 1.002 | 1.004 | | | |
| <i>p</i> -val (<i>t</i>) | 0.046 | 0.004 | 0.026 | 0.094 | 0.070 | 0.013 | 0.070 | 0.067 | 0.005 | 0.086 | 0.112 | 0.189 | 0.041 | 0.057 | | | |
| p-val (F) | 0.818 | 0.000 | 0.000 | 0.010 | 0.977 | 0.000 | 1.000 | 0.553 | 0.002 | 0.159 | 0.110 | 0.984 | 0.101 | 0.183 | | | |

Table A.5 (continuation). Out-of-Sample *BAB* Forecasting Power of VIX² and MOVE² against Alternative Standard Predictors, May 1988-June 2017.

Tables A.1 through A.5 show the out-of-sample forecast accuracy of either VIX² or MOVE², comparing the unrestricted model that contains either VIX² or MOVE2 and the additional standard predictor with the restricted model that includes only the standard predictor where this predictor can also be VIX² or MOVE². *RMSE* is the relative mean-squared forecasting error that compares the mean-squared

forecasting error of the restricted model and the mean-squared forecasting error of the unrestricted model. The *p*-value (*t*) and *p*-value (*F*) are two statistics to test the equal forecasting ability of the two models associated with expressions (28) and (30). They are obtained by an efficient bootstrap method for simulating asymptotic critical values. We always control on individual basis for the lagged of the dependent variable, *TERM*, *DEF*, *DY*, the *HJ* volatility bound of Nieto and Rubio (2014) and *TED*. We report the *t*-statistic from Newey-West/ HAC standard errors.